

Physical Meaning and Experimental Check of a Variational Principle for Macro-to-Micro Transition

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1. Boundary conditions in micro-macro problems

Basic requirement for the applicability of a micro-macro model:

Hill's macro-homogeneity condition: the micro-fields $\boldsymbol{\sigma}(\mathbf{x})$, $\mathbf{d}(\mathbf{x})$ fluctuate around well-defined macro-averages $\boldsymbol{\Sigma}$ and \mathbf{D} .

(Actually $\boldsymbol{\Sigma}$ and \mathbf{D} usually not uniform, but vary slowly.)

Domain to be considered: any Representative Volume Element (RVE) . But even in a macro-homogeneous part, this means:

Boundary value unknown, even undetermined

(varies from an RVE to another one)

Usual implicit postulate: the *exact* boundary data do not matter

→ assume data corresponding to a uniform field,

e.g. velocity $\mathbf{v}(\mathbf{x}) = \mathbf{D}\cdot\mathbf{x}$ for \mathbf{x} at the boundary of the RVE

2. "Stochastic" features of the microscopic fields

A deformation process with non-linear constitutive equation =

An initial value Pb.

for a *non-linear* "dynamical" (= differential) system:

$$\frac{dY}{dt} = f(Y(t), t).$$

$Y(t) \equiv$ [displacement field $\mathbf{u}(\mathbf{x}^0, t)$, internal variables field $\mathbf{X}(\mathbf{x}^0, t)$]

$\Rightarrow \frac{dY}{dt} =$ [velocity field $\mathbf{v}(\mathbf{x}^0, t)$, evolution rate $\dot{\mathbf{X}}(\mathbf{x}^0, t)$]

= function of current $Y = (\mathbf{u}, \mathbf{X})$ and current boundary data for \mathbf{v}

↓

an "external forcing"

Non-linear constitutive equations \Rightarrow non-linear system,

$$f(Y, t) \neq A(t) \cdot Y + B(t)$$

\Rightarrow Possible sensitivity to initial/boundary data (loss of stability?)

Recall: loss of stability in mechanics of materials appears as *strain localization*. (Cf. Considère's diffuse necking criterion.)

Microscopic strain localization is indeed the *rule* in plasticity (also in macro-homogeneous situations) :

- dislocation cells, | organized in
- slip lines, microscopic shear bands. | characteristic patterns

Consequences

1) The *microscopic strain field* (hence also the stress) has some *non-deterministic* features characteristic of non-linear dynamical systems, with "*self-organized*" structures emerging.

2) One should not simply *assume* some particular boundary data (e.g. $\mathbf{v}(\mathbf{x}) = \mathbf{D}\cdot\mathbf{x}$, $\mathbf{x} \in \partial\Omega$) without checking the effect of other data

3) The *strain-rate heterogeneity*, $h \equiv \langle \|\mathbf{d} - \langle \mathbf{d} \rangle\| \rangle$,
depends on the amount of microscopic localization.

Hence h is hardly predictable \Rightarrow should be added to the microscopic information to make the data.

3. The principle of minimum heterogeneity

in the proposed micro-macro model

Microscopic constitutive eqns. assumed to derive from a *potential*:

e.g. for plasticity or viscoplasticity, $\boldsymbol{\sigma} = \frac{\partial u}{\partial \mathbf{d}}(\mathbf{d}, \mathbf{X})$.

\mathbf{X} : variables that make u inhomogeneous ($\mathbf{X}=\mathbf{X}(\mathbf{x})$). E.g. crystal orientation, dislocation density, ...

Constituents: zones with constant \mathbf{X} , say $\Omega_1, \dots, \Omega_n$ (for $\mathbf{X}_1, \dots, \mathbf{X}_n$)

$f_k \equiv \text{Vol}(\Omega_k)/\text{Vol}(\text{RVE})$: volume fraction of constituent (k)

\mathbf{D}_k : volume average of the strain-rate \mathbf{d} in constituent (k)

Unknown of the macro-to-micro transition: the distribution (\mathbf{D}_k).

Let (\mathbf{D}^*_k) be a candidate for this distribution.

\Rightarrow average $\mathbf{D}^* \equiv f_1 \mathbf{D}^*_1 + \dots + f_n \mathbf{D}^*_n$ must be the macro-tensor \mathbf{D} .

Heterogeneity of the distribution:

$$h = h((\mathbf{D}^*_k)) \equiv f_1 \|\mathbf{D}^*_1 - \mathbf{D}^*\| + \dots + f_n \|\mathbf{D}^*_n - \mathbf{D}^*\|.$$

Model: Search $U_r(\mathbf{D}) \equiv \text{Min} [f_1 u_1(\mathbf{D}^*_1) + \dots + f_n u_n(\mathbf{D}^*_n)]$

under constraints $\mathbf{D}^* = \mathbf{D}$ and $h = r$. (r assumed given).

Theorem: For any \mathbf{D} , there exists a generically unique value $r_0(\mathbf{D})$ such that $U_{r_0}(\mathbf{D}) = U(\mathbf{D})$, the exact value of the macro-potential.

Micro-to-macro transition: the mere problem is to find r_0 . One postulates a simple dependence $r_0 = r_0(\mathbf{D})$, e.g. $r_0 = a \|\mathbf{D}\|$, and one "adjusts" a from *one* mechanical test. (In easy cases, a is guessed.)

Macro-to-micro transition: one has to assume that the distribution solution $(\mathbf{D}^{\text{sol}}_k)$ is "the actual" distribution (\mathbf{D}_k) .

Theorem: the assumption $(\mathbf{D}^{\text{sol}}_k) = (\mathbf{D}_k)$ amounts to assuming a

Principle of minimum inhomogeneity:

Among distributions (\mathbf{D}^*_k) that have the relevant macro-average \mathbf{D} and that lead to the correct value of the macro-potential

[i.e. $U(\mathbf{D}) = f_1 u_1(\mathbf{D}_1) + \dots + f_n u_n(\mathbf{D}_n) = f_1 u_1(\mathbf{D}^*_1) + \dots + f_n u_n(\mathbf{D}^*_n)$],

the actual distribution (\mathbf{D}_k) has the least heterogeneity h .

4. The maximum entropy principle

Consider a system of N "elementary constituents" (molecules in the kinetic theory of gases/ *Here*: small crystals with same volume)

The state of each element^y const^t (velocity, position / *orientation*, *strain-rate*) is in one among M possible boxes, with $1 \ll M \ll N$.

Let l_i ($i = 1, \dots, M$) be the number of elem^y const^{ts} in box (i).

The corresponding fraction is $p_i = l_i/N$ ($p_1 + \dots + p_M = 1$).

Macro-state: (pressure, density) / *here*: [volume fractions of the orientations f_k ($k = 1, \dots, n$), macro strain-rate \mathbf{D} , macro-power \dot{W}].

Must be computable from the probability distribution (p_i).

A given probability distribⁿ (p_i) [or a given distribⁿ (l_i), $l_i = Np_i$] may be obtained by a large number Z of distinct *configurations*: e.g. with $N=12$ elem^y const^{ts} and $M=5$ boxes, $(l_i)=(2,1,3,1,5)$, as

Statistical Mechanics: the "real" distribution = the one that may be obtained by the *largest* number Z of distinct configurations compatible with the given macro-state.

Number of configur^{ns} (*ignoring the constraint* of the macro-state):

$$Z = \frac{N!}{l_1! \dots l_M!} \quad \Rightarrow \quad \frac{1}{N} \text{Log} Z \approx - \sum_{i=1}^M p_i \text{Log} p_i \equiv S$$

S : *statistical entropy*.

\Rightarrow In the "no constraint" case, $Z = \max \Leftrightarrow S = \max$.

Resulting distribution: *uniform*, $p_i = 1/M$ for $i = 1, \dots, M$.

But the " $S = \max$ " principle is more general (now central in statistical physics). With constraints (= with *additional information*, e.g. macroscopic information): amounts to *selecting the **broadest** probability distribution compatible with the available information* (Jaynes 1957). I.e., the "unbiased choice".

5. Minimum heterogeneity vs. maximum entropy (polycrystal)

Micro-state: (orientation \mathbf{R} , strain-rate \mathbf{d})

$$\mathbf{R} \in \{\mathbf{R}_1, \dots, \mathbf{R}_n\}, \quad \mathbf{d} \in \{\mathbf{D}^1, \dots, \mathbf{D}^m\}, \quad (\mathbf{D}^1 + \dots + \mathbf{D}^m)/m = \mathbf{D}.$$

Let $l_i = l_k^j =$ number of elementary crystals with μ -state $(\mathbf{R}_k, \mathbf{D}^j)$:

$$\sum_{j,k} l_k^j = N, \quad i \Leftrightarrow (j, k), \quad p_k^j = l_k^j / N.$$

The volume fractions of the orientations are given (= the texture):

$$N_k \equiv l_k^1 + \dots + l_k^m, \text{ or equivalently } f_k \equiv N_k / N, \text{ are known.}$$

Average strain-rate in orientation \mathbf{R}_k :

$$\mathbf{D}_k \equiv (l_k^1 \mathbf{D}^1 + \dots + l_k^m \mathbf{D}^m) / N_k.$$

$$\text{Heterogeneity: } h \equiv \sum_k f_k \|\mathbf{D}_k - \mathbf{D}\| = \sum_k \left\| \sum_j p_k^j \mathbf{D}^j - f_k \mathbf{D} \right\|.$$

Since $p_k^1 + \dots + p_k^m = f_k$, the "S = max" principle selects, in average over k and accounting for the constraints, the (p_k^j) distribution closest possible to the uniform distribution $p_k^j = f_k/m$.

But since $(\mathbf{D}^1 + \dots + \mathbf{D}^m)/m = \mathbf{D}$, this means simply h minimum !!

Conclusions

- 1) In an inelastically deformed heterogeneous material, the microscopic fields have some *non-deterministic* features. These make difficult to envisage a micro-macro problem merely as a boundary value problem for a differential equation.
- 2) The proposed variational model is consistent with this remark: it considers the *strain heterogeneity* as a necessary *input* of the micro-macro model, in addition to the microscopic information.
- 3) The *principle of minimum inhomogeneity*, that justifies the macro-to-micro transition in the model, may be seen as a consequence of the *maximum entropy principle*.
- 4) The proposed model compares favourably with other models as to the *experimental agreement* - for the deformation textures of steels (other metals currently investigated).