



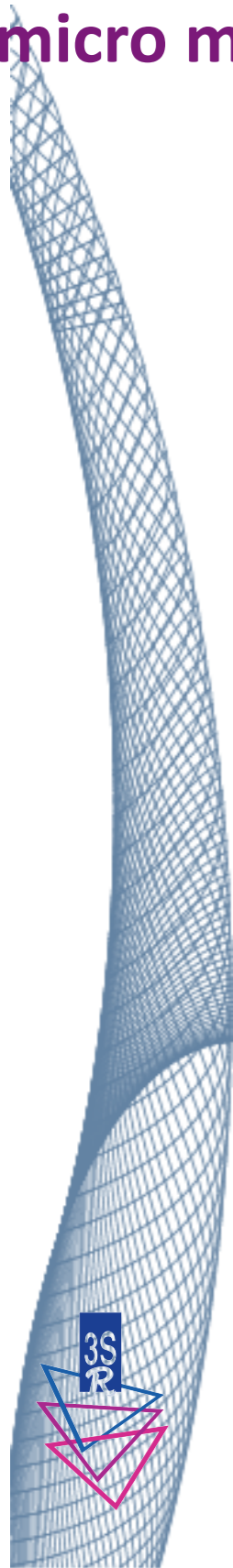
# Homogenization from the viewpoint of the periodic media Principles and contributions

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Sols Solides Structures et Risques



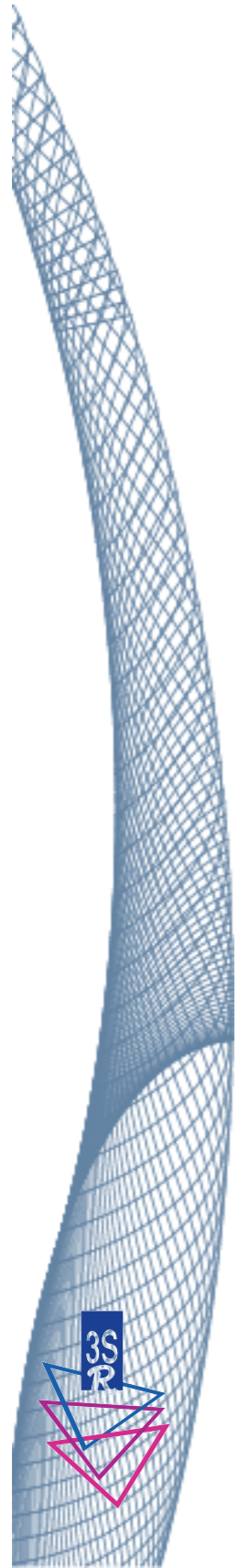
# What is meant by homogenization ? or upscaling or micro macro methods

To define for a **finely heterogeneous** medium,  
"macroscopic" representative quantities  
and equations that enable to determine them



The keyword is **separation of scales**

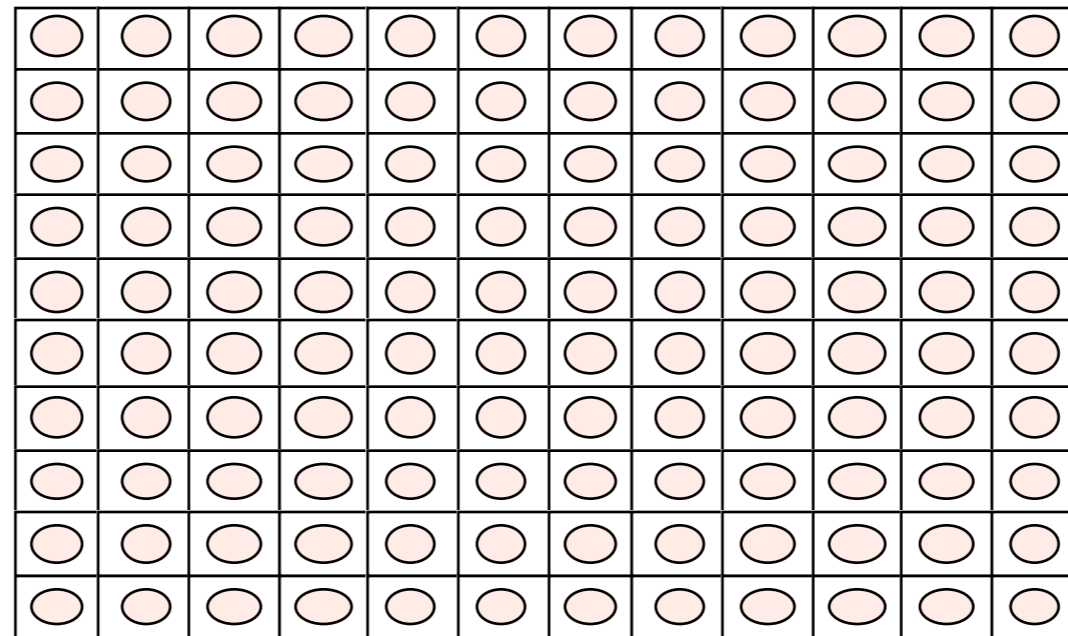
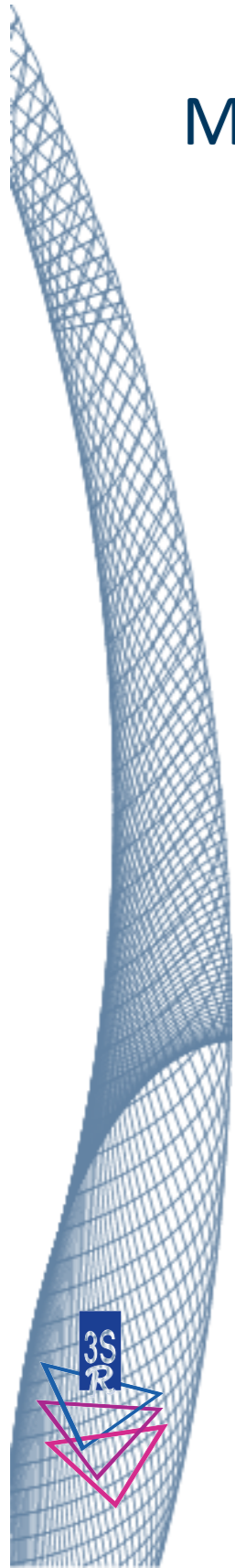
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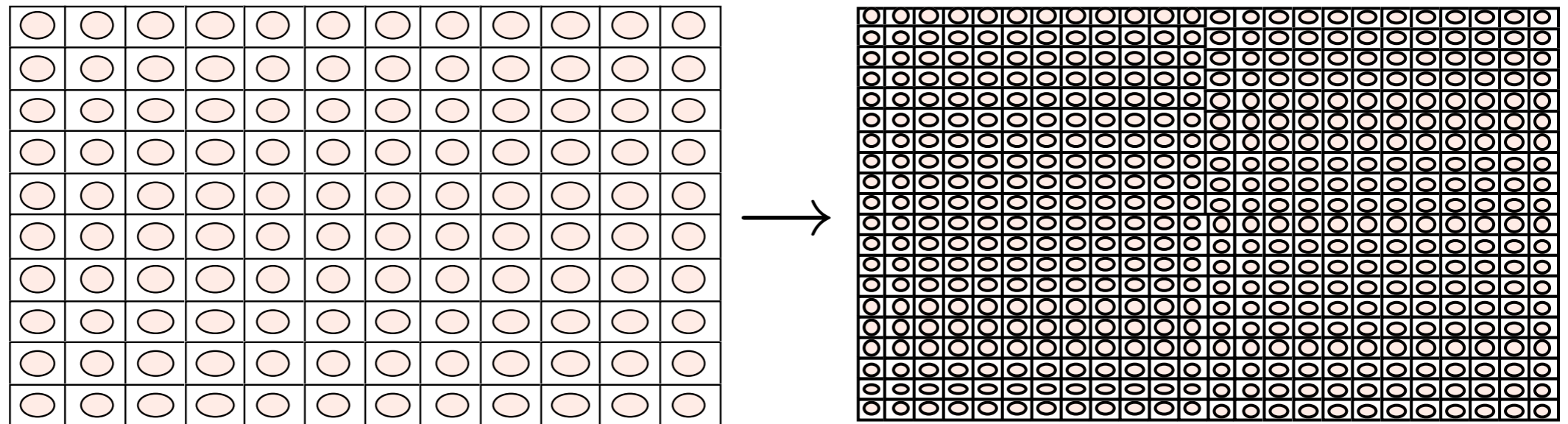
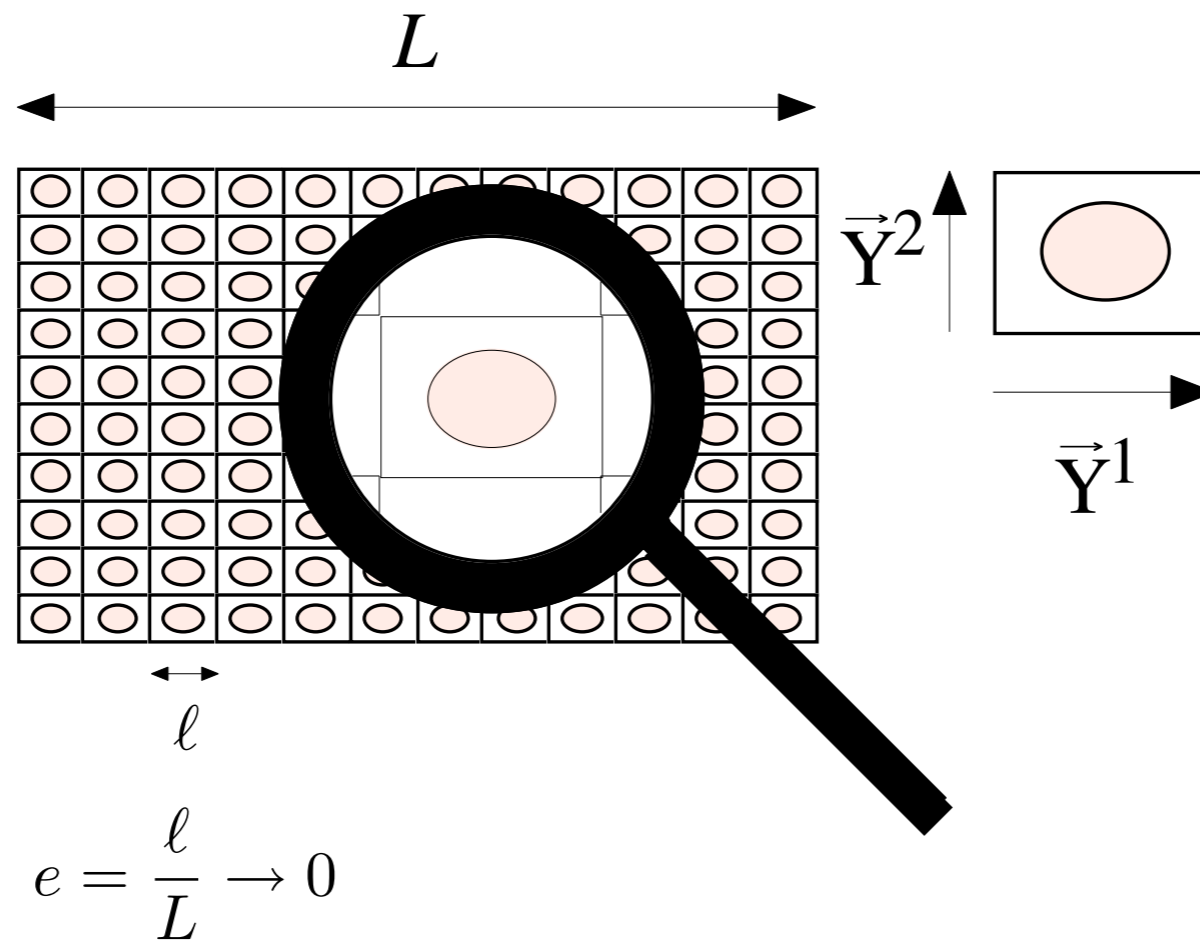
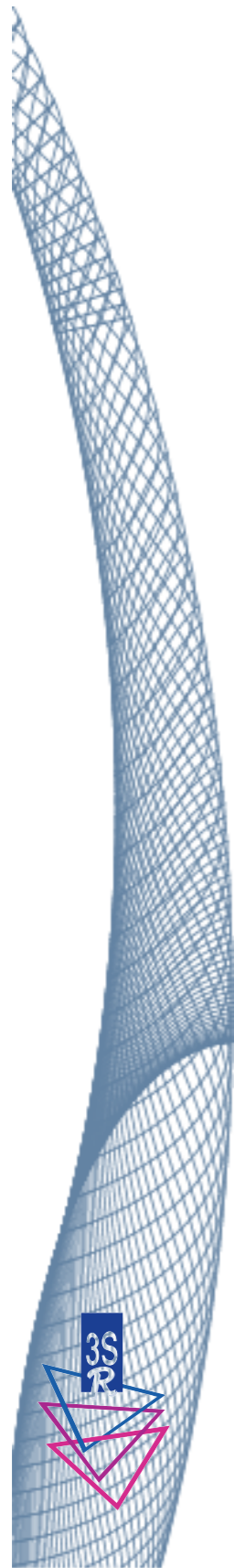
# Periodic media

Media with periodically distributed heterogeneities





# Finely periodic media - asymptotic method

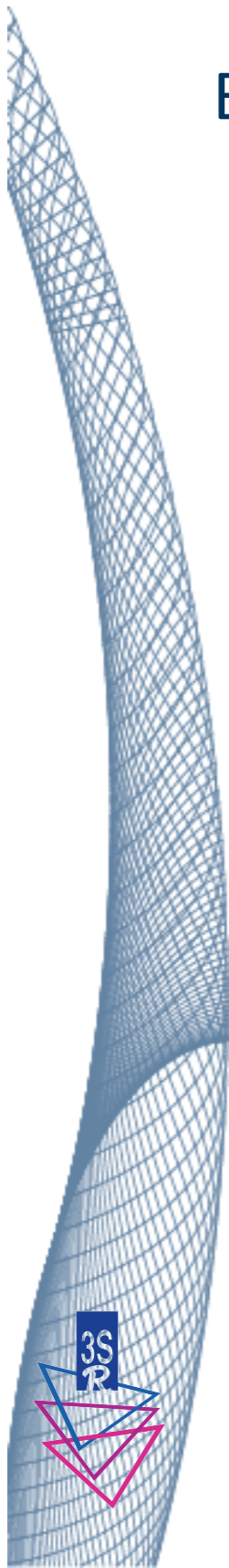


## Periodic media ? Why ?

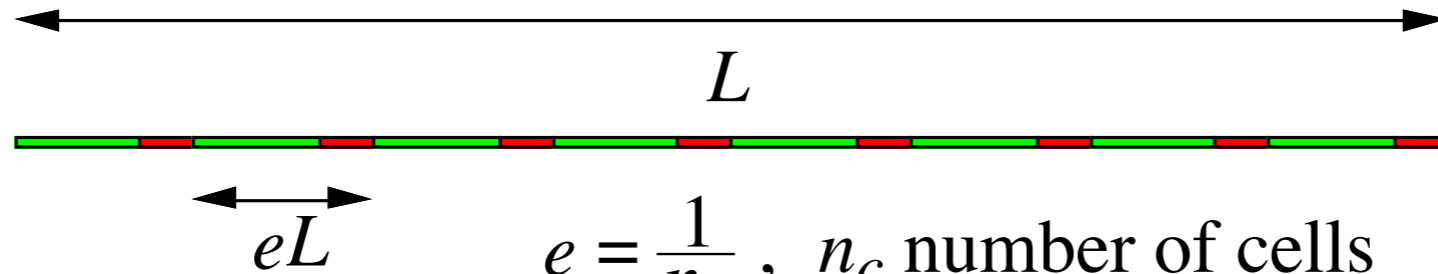
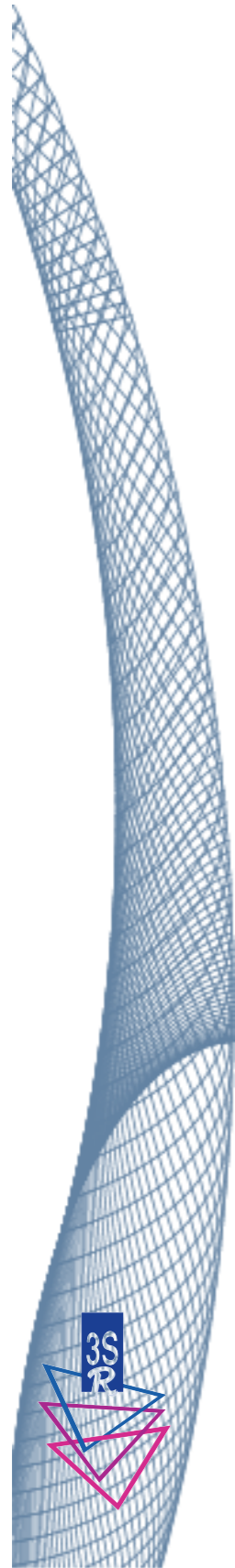
Because there are natural or manufactured periodic media



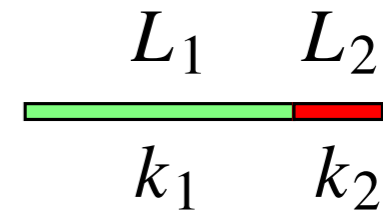
Mainly because the method which has been widely used is very robust, it has many interesting features and can bring interesting perspectives to homogenization in general



# 1D periodic bar



$$e = \frac{1}{n_c}, \quad n_c \text{ number of cells}$$



$$0 = \frac{dN}{dx} + f$$

$$N = k^e(x) \frac{du}{dx}$$

$$k^e(x) = k\left(\frac{x}{e}\right), \quad k(y) = \begin{cases} k_1 & 0 < y < L_1 \\ k_2 & L_1 < y < L \end{cases}$$

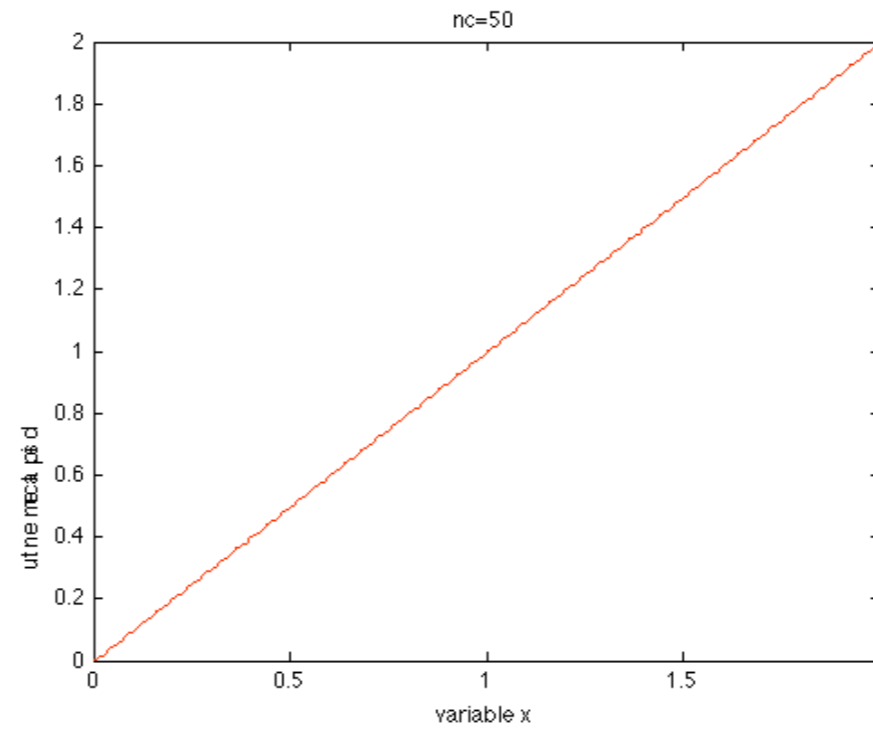
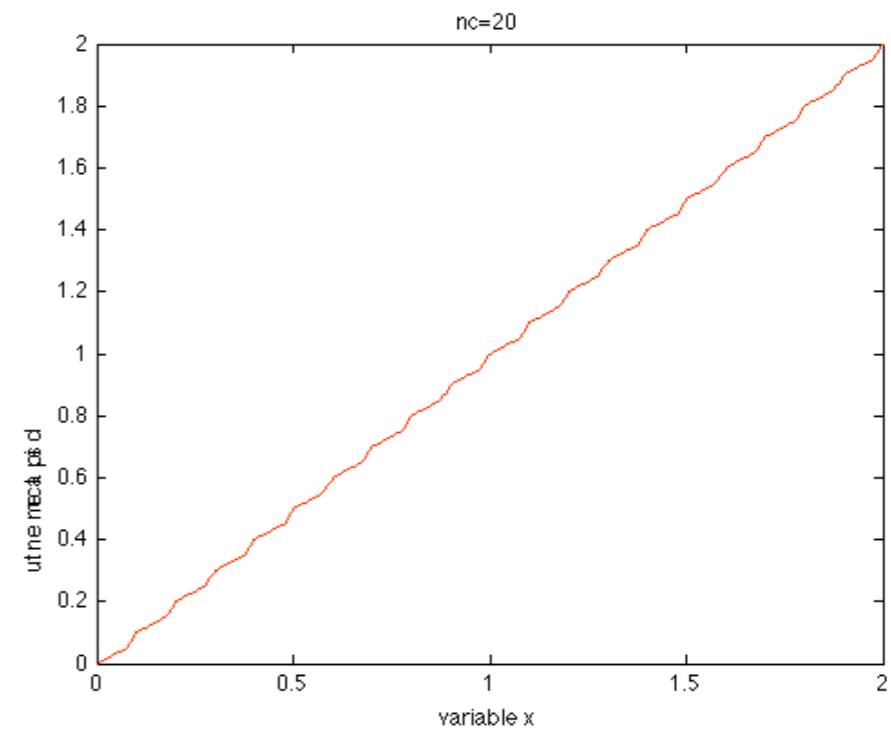
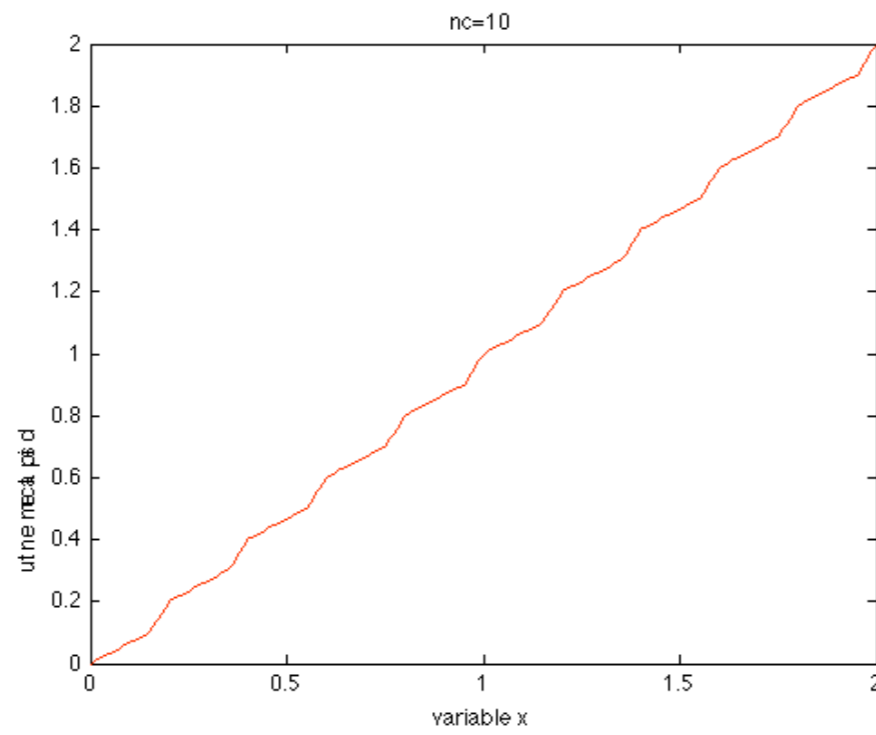
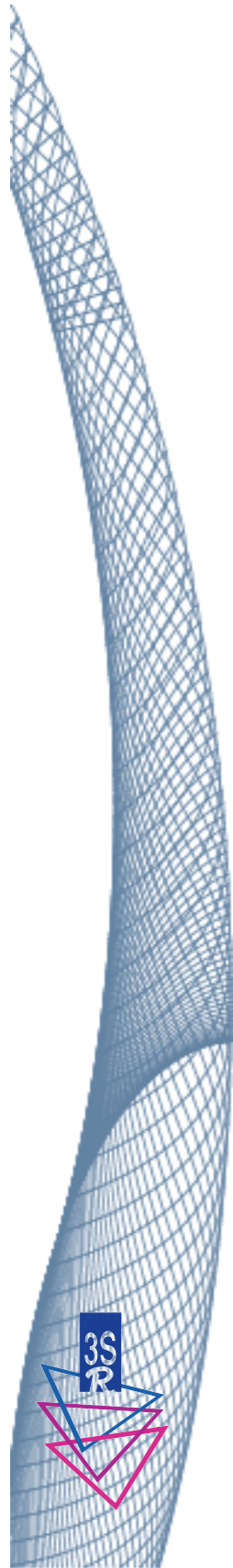
$$u(0) = 0, \quad N(L) = F$$

This problem can be easily solved



# 1D periodic bar

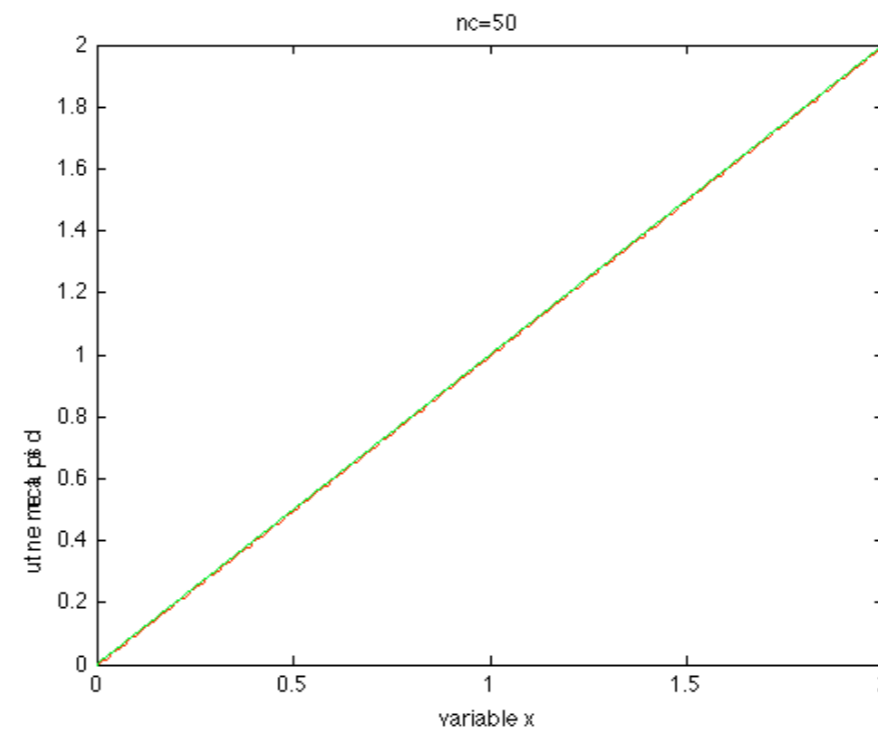
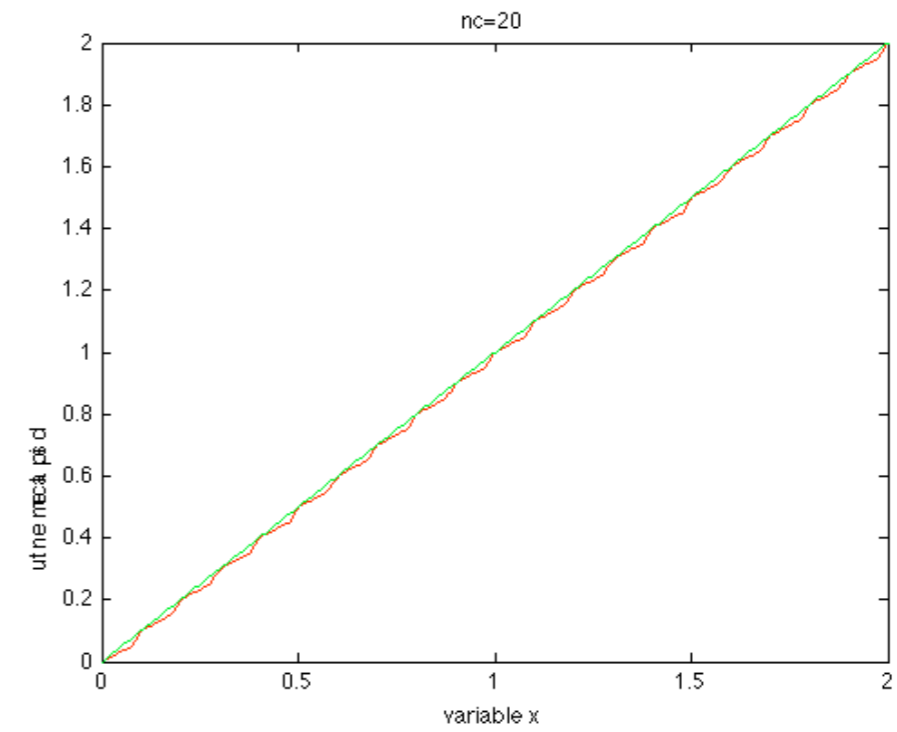
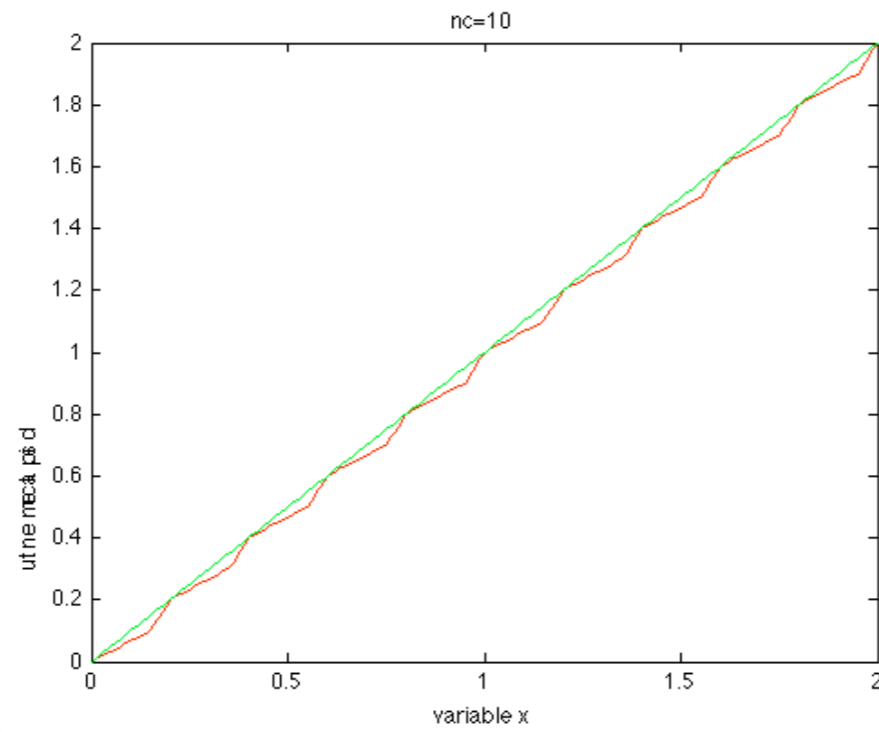
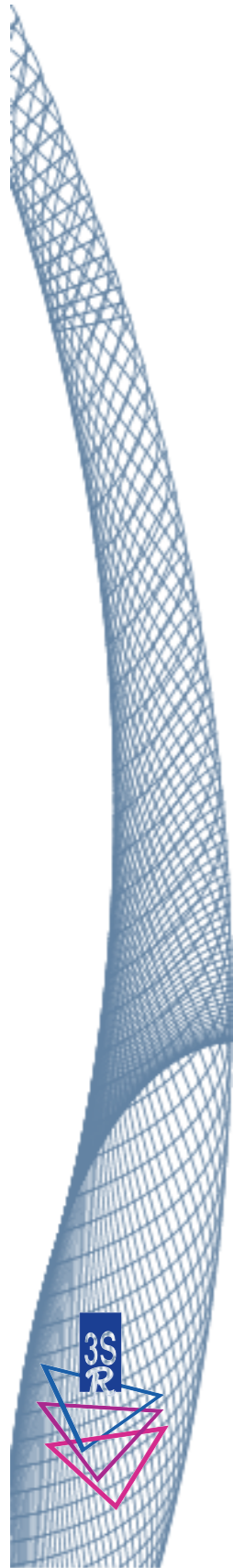
$$f = 0$$





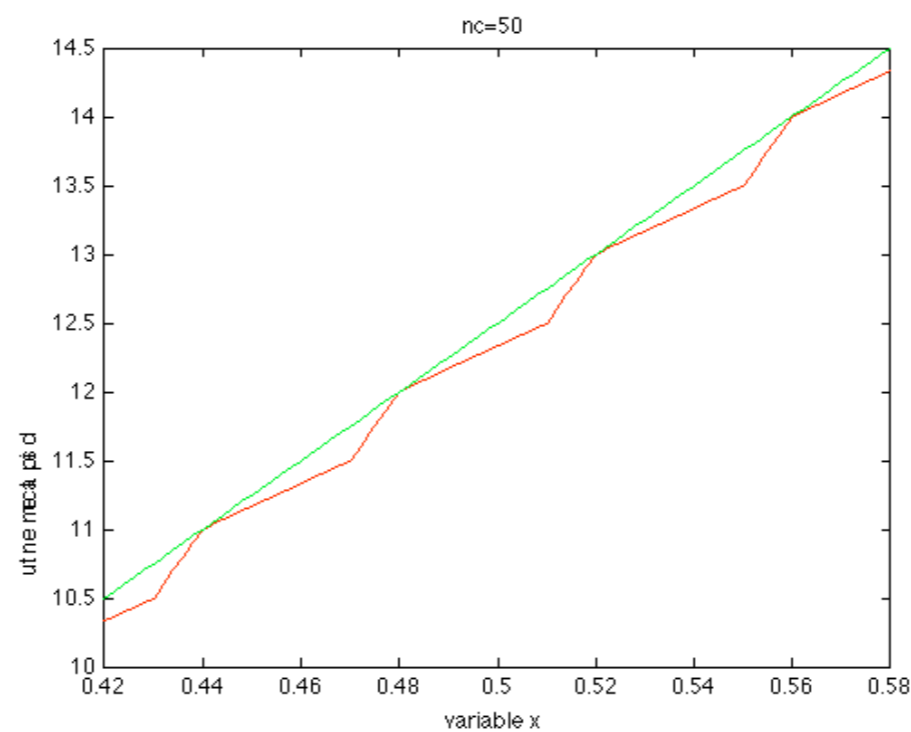
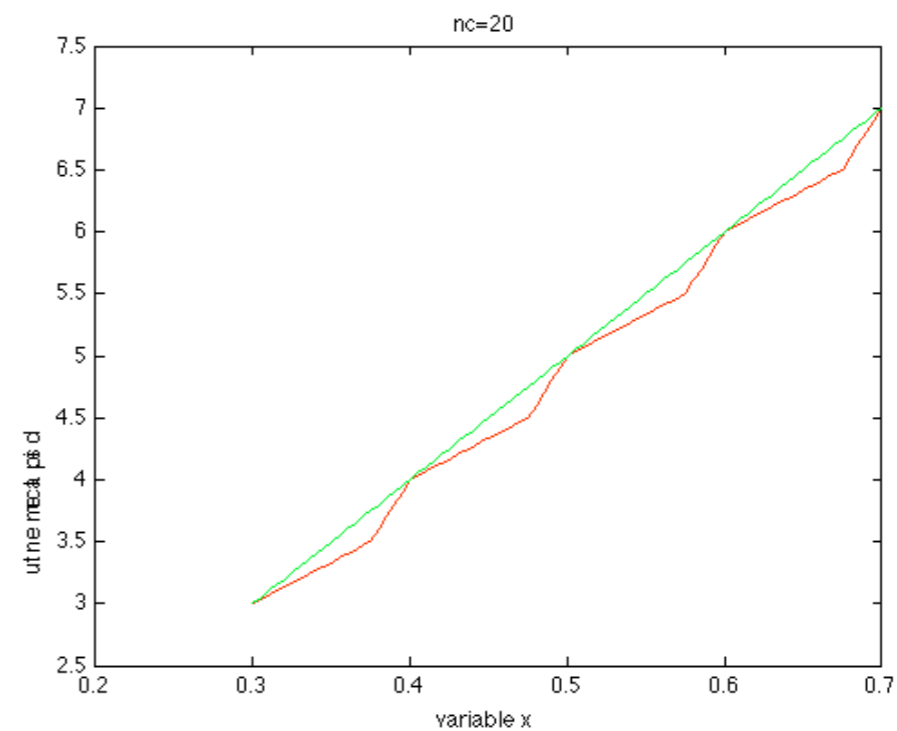
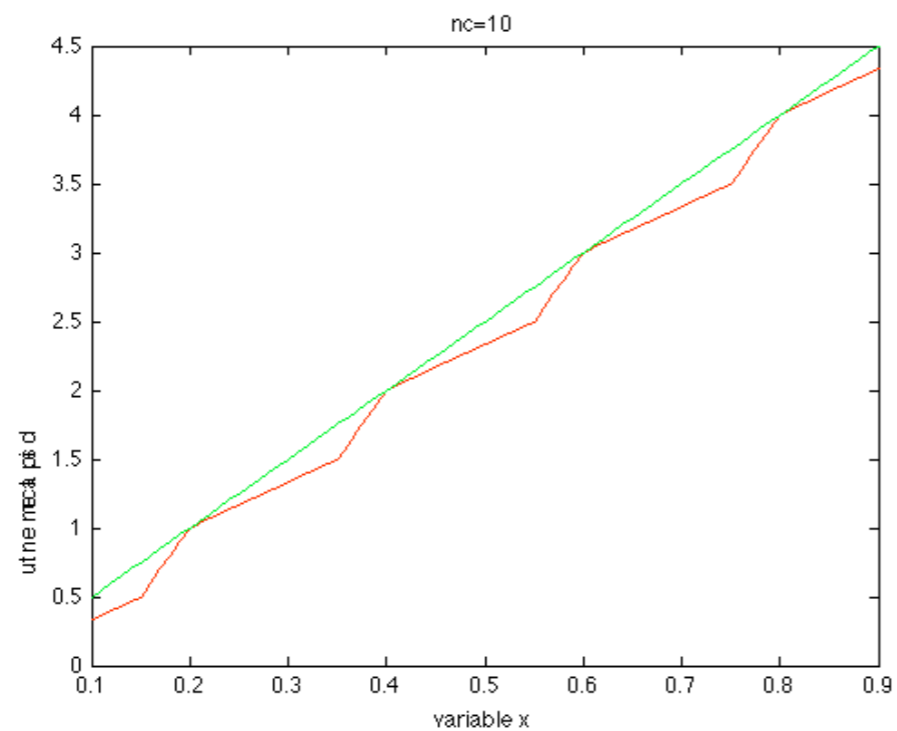
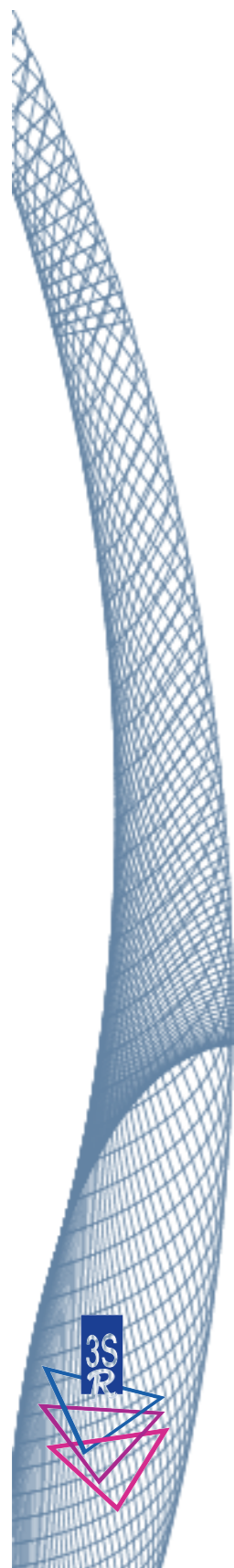
# 1D periodic bar

## Convergence to the homogenized solution



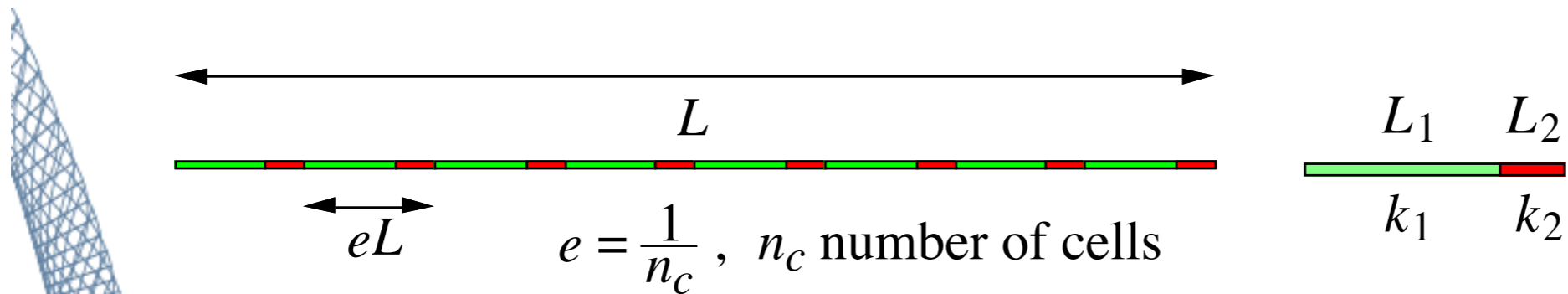
# 1D periodic bar

Zoom X Nc around  $x = 0.5$





# 1D periodic bar - Heuristic homogenization



At the small scale the normal stress  $N$  is almost constant:

$$\frac{dN}{dx} = 0$$

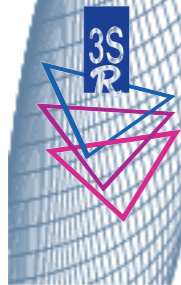
and the variation of the displacement on a length equal to the period  $eL$  corresponds to the macroscopic strain:

$$u(x + eL) - u(x) = \varepsilon^M eL$$

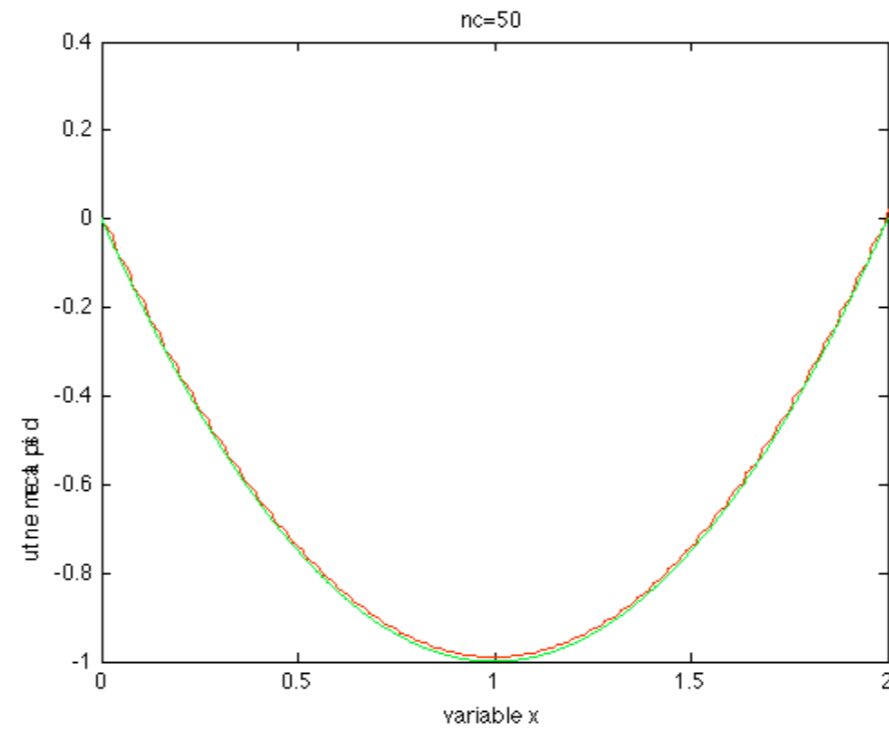
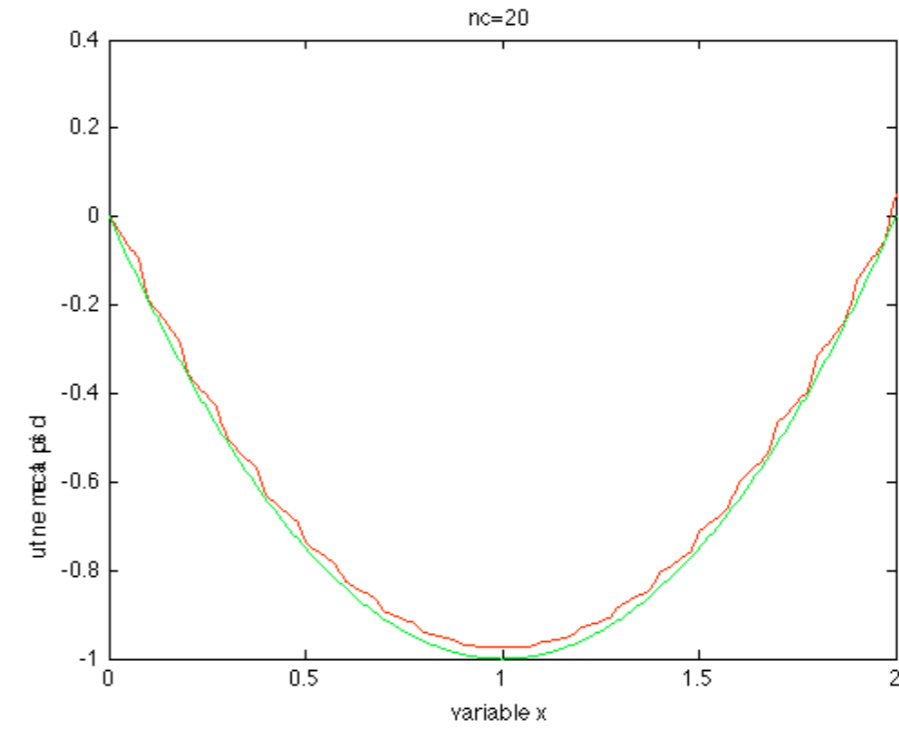
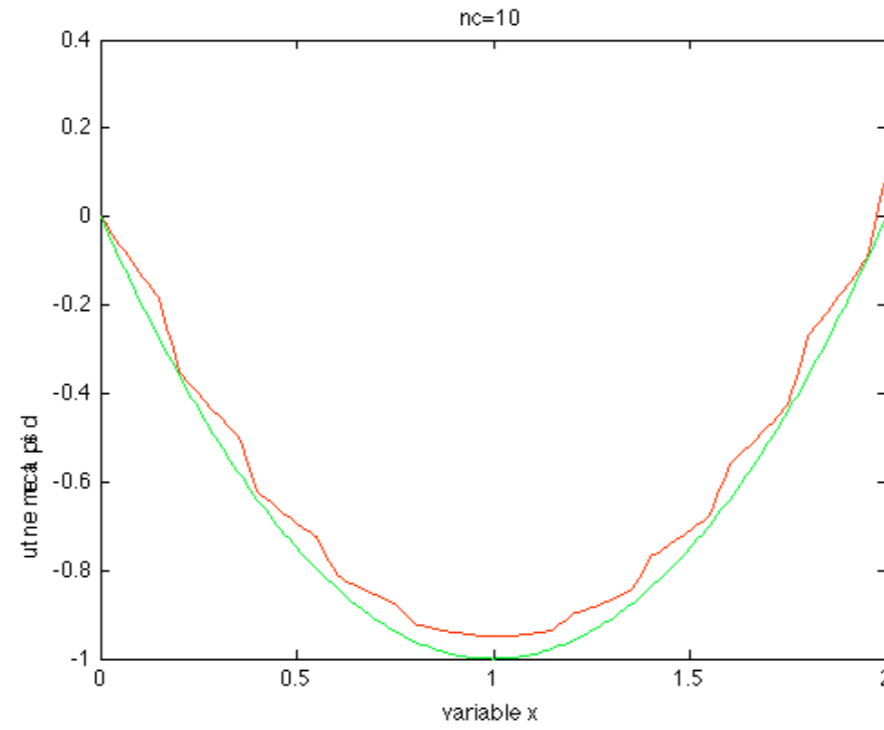
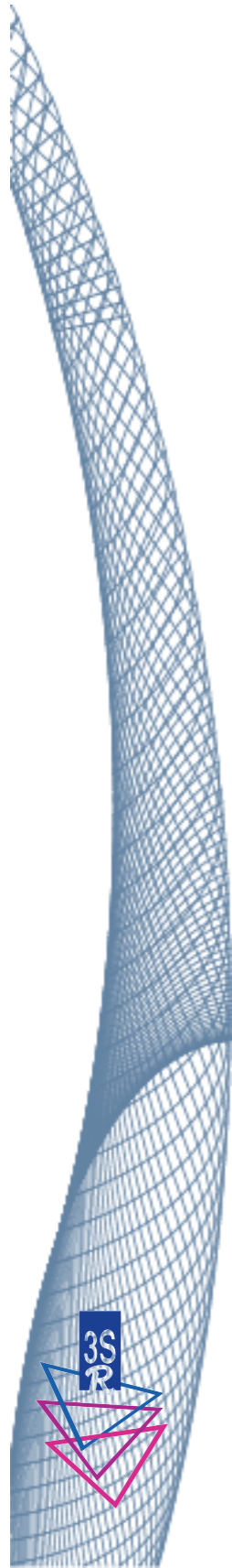
The integration of the constitutive equation  $N = k^e(x) \frac{du}{dx}$  yields:

$$\varepsilon^M = \frac{N}{eL} \int_x^{x+eL} \frac{1}{k^e(\xi)} d\xi = \frac{1}{L} \left( \frac{L_1}{k_1} + \frac{L_2}{k_2} \right) N$$

Which is the **equivalent macroscopic constitutive equation**



# 1D periodic bar - Case of $f = -2$



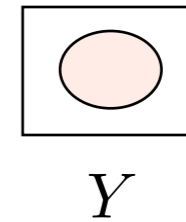
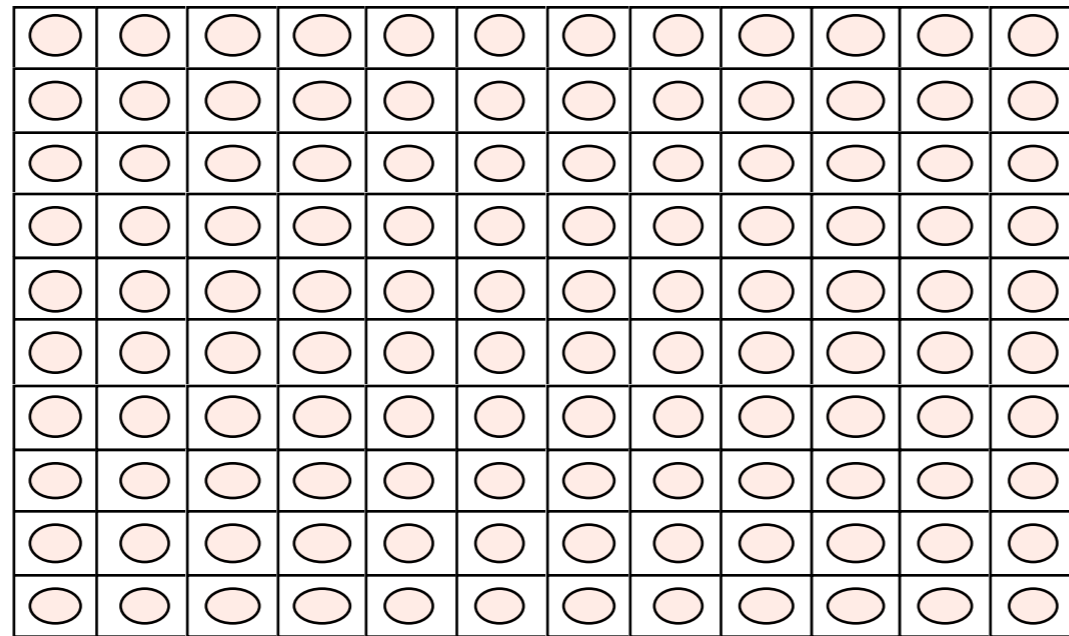


## 2D Elastic periodic medium

$$\operatorname{div} \sigma^e + \vec{f} = 0 \text{ in } \Omega$$

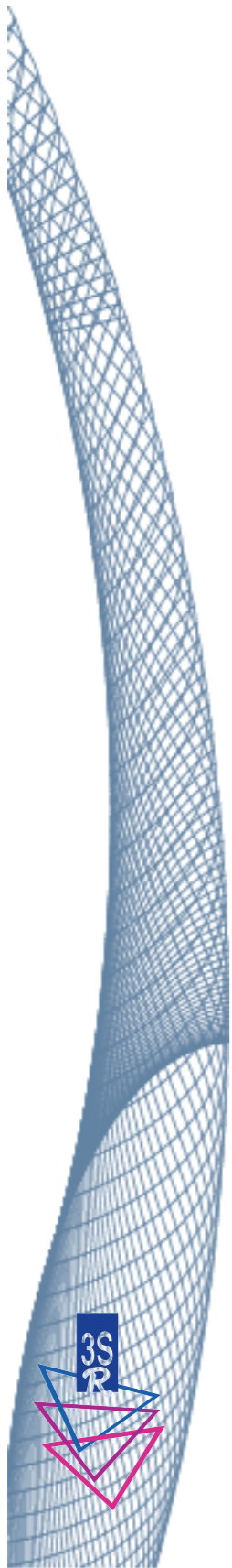
$$\sigma^e = C \left( \begin{array}{c} \vec{x} \\ e \end{array} \right) \epsilon(\vec{u}^e) \text{ in } \Omega$$

+ boundary conditions on  $\partial\Omega$



The 4th order tensor  $C(\vec{y})$  is  $Y$  periodic

$$e \rightarrow 0$$

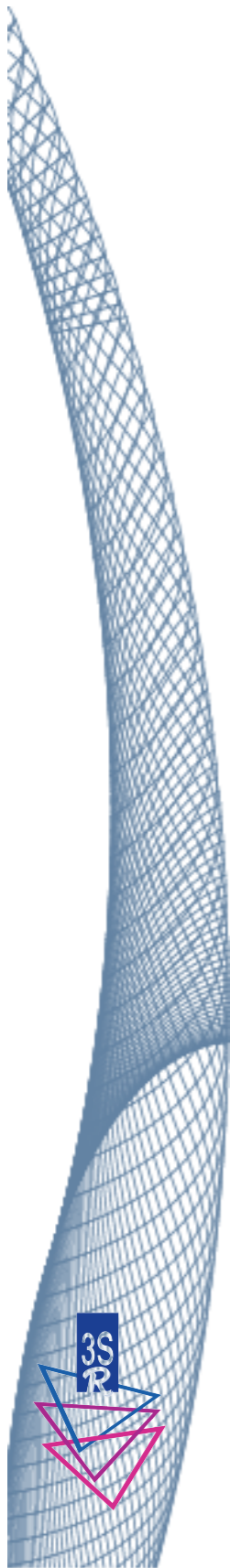
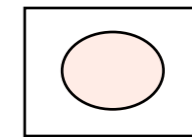
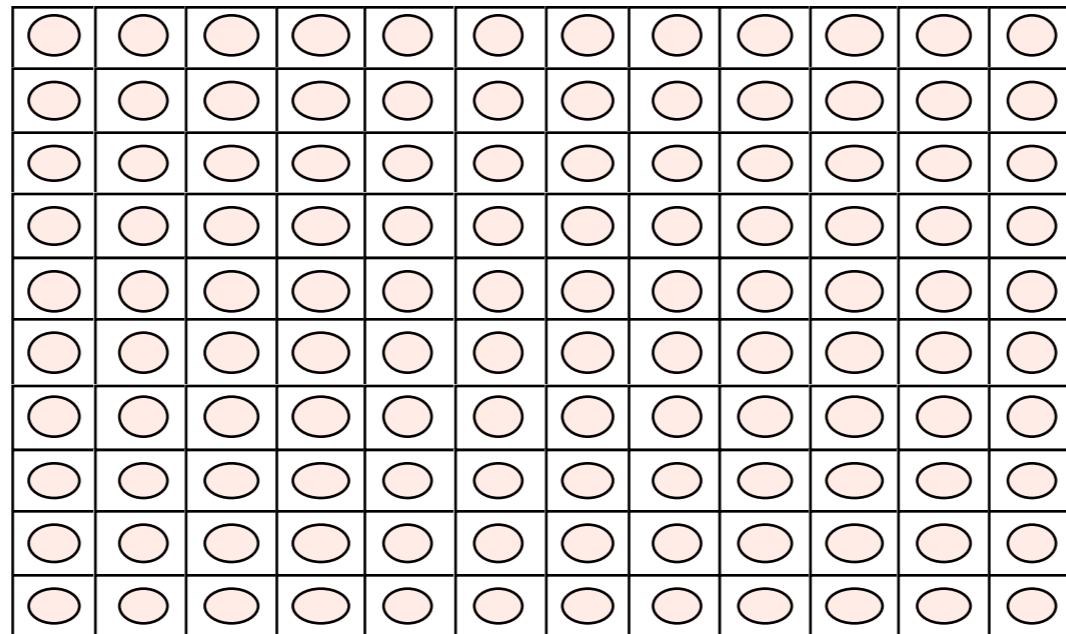


# Double scale asymptotic expansion

$$\vec{u}^e(\vec{x}) = \vec{u}^{(0)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + e\vec{u}^{(1)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + e^2\vec{u}^{(2)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + \dots$$

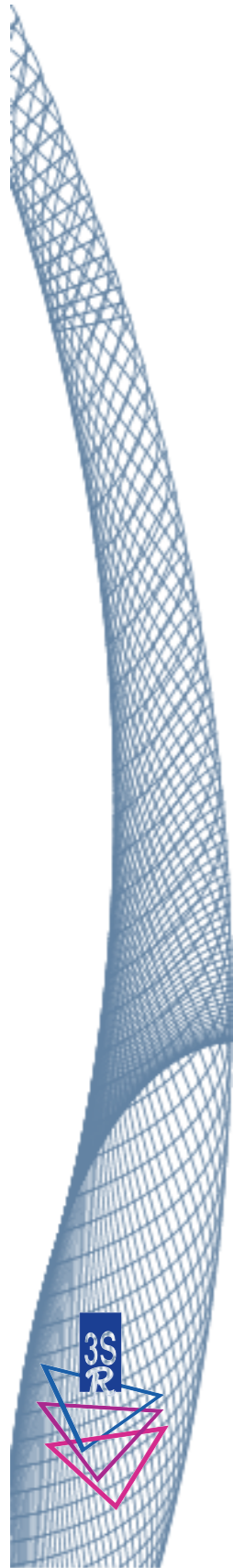
The  $\vec{u}^{(k)}(\vec{x}, \vec{y})$  are  $Y$  periodic so the  $\vec{u}^{(k)}\left(\vec{x}, \frac{\vec{x}}{e}\right)$  are almost  $eY$  periodic

Slow  $x$  and fast  $y$  variables





# Double scale asymptotic expansion



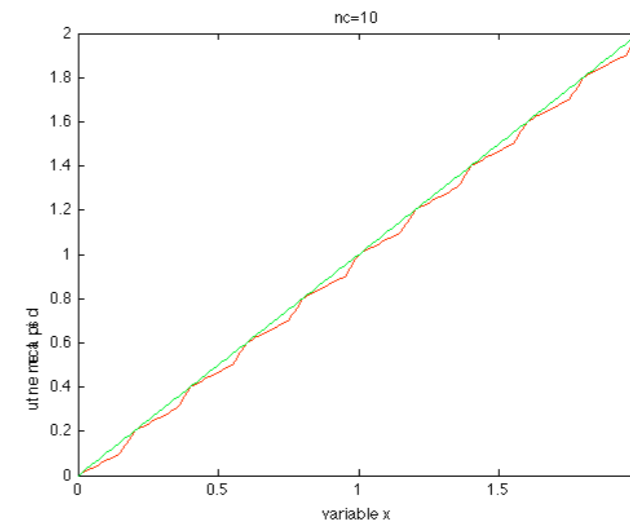
It turns out that  $\vec{u}^{(0)}$  does not depend on  $\vec{y}$

$$\vec{u}^e(\vec{x}) = \vec{u}^{(0)}(\vec{x}) + e\vec{u}^{(1)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + e^2\vec{u}^{(2)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + \dots$$

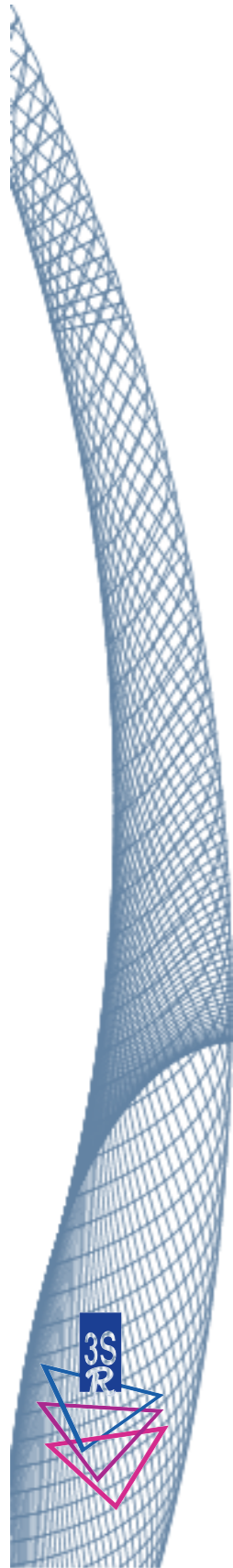
$\vec{u}^{(0)}(\vec{x})$  is the macroscopic displacement field

and, up to higher terms, the displacement  $\vec{u}^e(\vec{x}) = \vec{u}^{(0)}(\vec{x}) + e\vec{u}^{(1)}\left(\vec{x}, \frac{\vec{x}}{e}\right)$

is equal to the macroscopic one + a small correction presenting fast variations



# Double scale asymptotic expansion



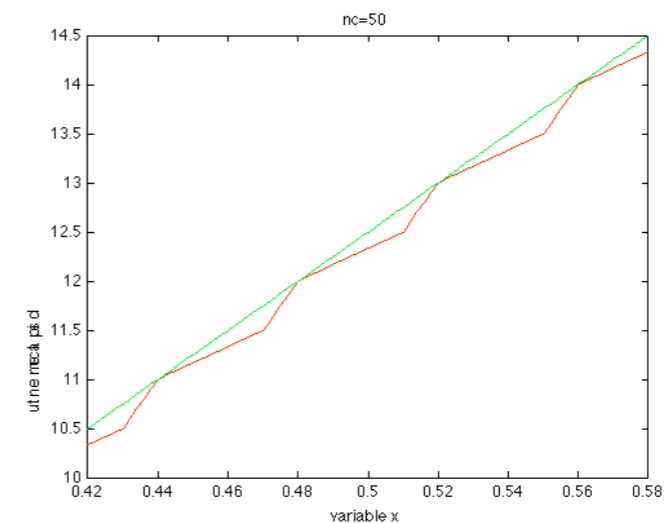
$$\vec{u}^e = \vec{u}^{(0)}(\vec{x}) + e\vec{u}^{(1)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + e^2\vec{u}^{(2)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + \dots$$

$$\nabla \vec{u}^e = \nabla^x \vec{u}^{(0)} + \nabla^y \vec{u}^{(1)} + e\left(\nabla^x \vec{u}^{(1)} + \nabla^y \vec{u}^{(2)}\right) + \dots$$

$$\epsilon(\vec{u}^e) = \epsilon^x(\vec{u}^{(0)}) + \epsilon^y(\vec{u}^{(1)}) + e\left(\epsilon^x(\vec{u}^{(1)}) + \epsilon^y(\vec{u}^{(2)})\right) + \dots$$

$$\sigma^e = \sigma^{(0)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + e\sigma^{(1)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + e^2\sigma^{(2)}\left(\vec{x}, \frac{\vec{x}}{e}\right) + \dots$$

$\sigma^{(k)}(\vec{x}, \vec{y})$  are  $Y$  periodic



## Expansion of the equilibrium equation

$$\sigma^e = \sigma^{(0)} \left( \vec{x}, \frac{\vec{x}}{e} \right) + e \sigma^{(1)} \left( \vec{x}, \frac{\vec{x}}{e} \right) + e^2 \sigma^{(2)} \left( \vec{x}, \frac{\vec{x}}{e} \right) + \dots$$

$$\operatorname{div} \sigma^e = \frac{1}{e} \operatorname{div}^y \sigma^{(0)} + \operatorname{div}^x \sigma^{(0)} + \operatorname{div}^y \sigma^{(1)} + e (\dots)$$

The balance equation  $\operatorname{div} \sigma^e + \vec{f} = 0$  expands into:

$$\frac{1}{e} \operatorname{div}^y \sigma^{(0)} + \operatorname{div}^x \sigma^{(0)} + \operatorname{div}^y \sigma^{(1)} + e (\dots) + \vec{f} = 0$$

which, by identification of the terms of same power, yields:

$$\operatorname{div}^y \sigma^{(0)} = 0$$

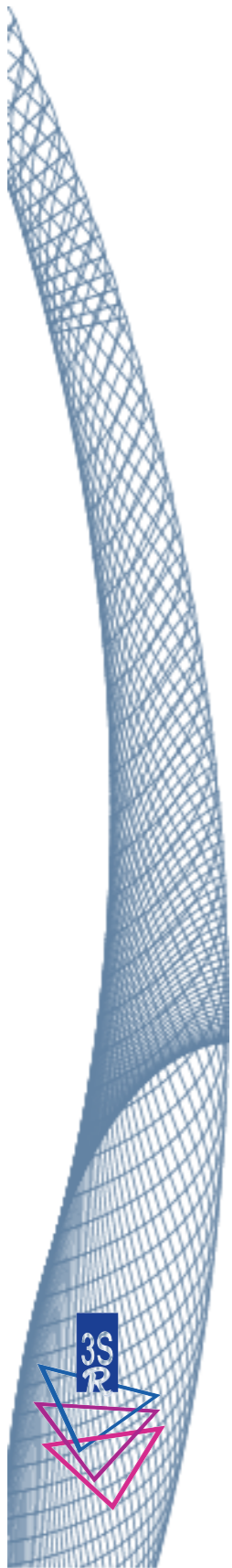
$$\operatorname{div}^x \sigma^{(0)} + \operatorname{div}^y \sigma^{(1)} + \vec{f} = 0$$

Macroscopic balance equation

$$\operatorname{div}^x \langle \sigma^{(0)} \rangle + \vec{f} = 0$$

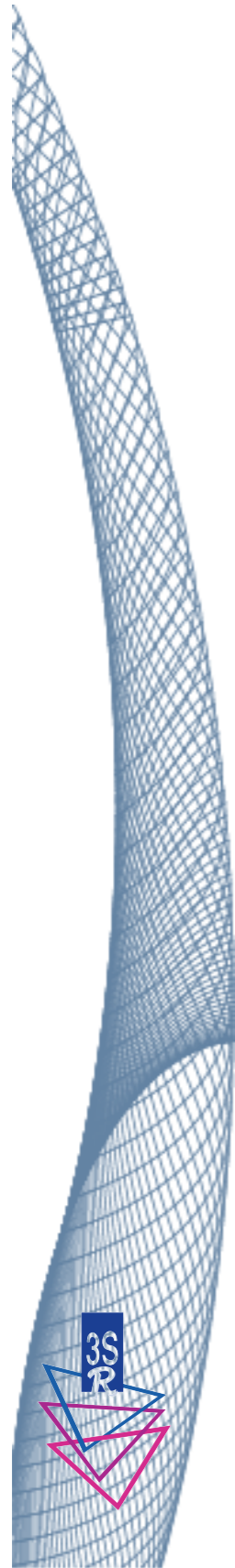
Macroscopic mean stress

$$\langle \sigma^{(0)} \rangle = \frac{1}{|Y|} \int_Y \sigma^{(0)} (\vec{x}, \vec{y}) \, dy$$





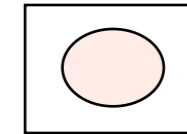
# Self equilibrium problem



$$\operatorname{div}^y \sigma^{(0)} = 0 \text{ in } Y$$

$$\sigma^{(0)} = C(\vec{y}) \left( \epsilon^x \left( \vec{u}^{(0)} \right) + \epsilon^y \left( \vec{u}^{(1)} \right) \right) \text{ in } Y$$

+ periodic boundary conditions on  $\partial Y$



The unknowns are  $\sigma^{(0)}$  and  $\vec{u}^{(1)}$

the datum is the macroscopic strain  $\epsilon^x \left( \vec{u}^{(0)} \right)$

The solving of this problem yields  $\vec{u}^{(1)}$  and  $\sigma^{(0)}$

and by averaging, the macroscopic stress  $\langle \sigma^{(0)} \rangle$

Which defines the equivalent macroscopic constitutive relation:

$$\epsilon^x \left( \vec{u}^{(0)} \right) \longrightarrow \vec{u}^{(1)} \text{ and } \sigma^{(0)} \longrightarrow \langle \sigma^{(0)} \rangle$$

# Self equilibrium problem - second form

$$\vec{\hat{u}}^{(1)}(\vec{y}) = \epsilon^x \left( \vec{u}^{(0)} \right) \cdot \vec{y} + \vec{u}^{(1)}(\vec{x}, \vec{y})$$

then:

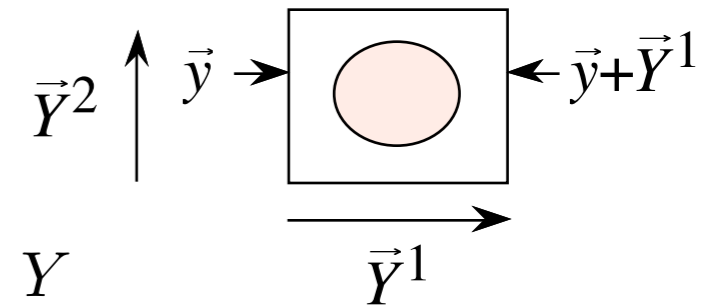
$$\nabla^y \vec{\hat{u}}^{(1)} = \epsilon^x \left( \vec{u}^{(0)} \right) + \nabla^y \vec{u}^{(1)}$$

the problem for  $\vec{\hat{u}}^{(1)}$  reads:

$$\operatorname{div}^y \sigma^{(0)} = 0 \text{ in } Y$$

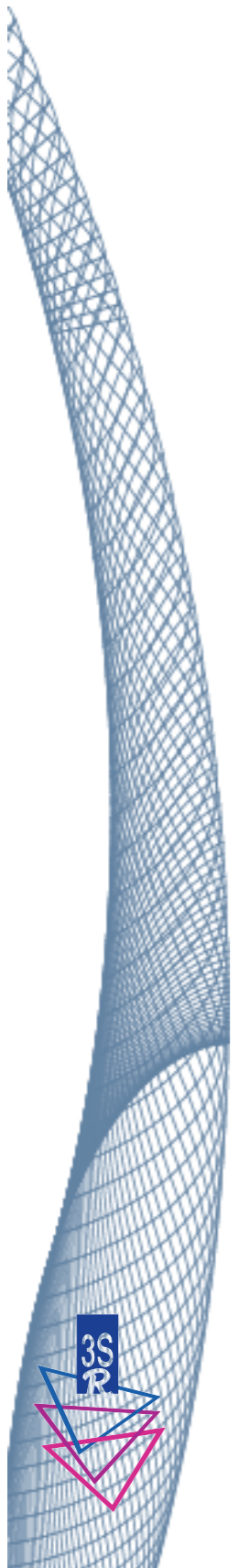
$$\sigma^{(0)} = C(\vec{y}) \epsilon^y \left( \vec{\hat{u}}^{(1)} \right) \text{ in } Y$$

$$\vec{\hat{u}}^{(1)}(\vec{y} + \vec{Y}^i) - \vec{\hat{u}}^{(1)}(\vec{y}) = \epsilon^x \left( \vec{u}^{(0)} \right) \cdot \vec{Y}^i \text{ on } \Gamma^i, i = 1, 2$$



Hill's lemma

$$\left\langle \sigma^{(0)} \right\rangle : \epsilon^x \left( \vec{u}^{(0)} \right) = \left\langle \sigma^{(0)} : \epsilon^y \left( \vec{\hat{u}}^{(1)} \right) \right\rangle$$



# Self equilibrium problem - third form on the real cell

The small parameter  $e = \ell/L$  is somehow arbitrary

Homothety from the expanded cell  $Y$  to the real cell  $Y_{\vec{x}}^e$  located by  $\vec{x}$

$$\vec{y} \leftrightarrow \vec{\xi} = e\vec{y}$$

Change of unknowns

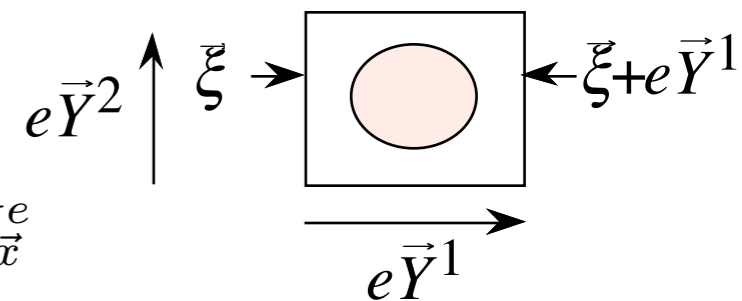
$$\vec{u}^{(1)}(\vec{\xi}) = e\vec{\tilde{u}}^{(1)}\left(\frac{\vec{\xi}}{e}\right) = e\left(\epsilon^x(\vec{u}^{(0)}) \cdot \frac{\vec{\xi}}{e} + \vec{u}^{(1)}\left(\vec{x}, \frac{\vec{\xi}}{e}\right)\right)$$

$$\vec{\sigma}^{(0)}(\vec{\xi}) = \vec{\sigma}^{(0)}\left(\vec{x}, \frac{\vec{\xi}}{e}\right)$$

$\vec{u}^{(1)}$  and  $\vec{\sigma}^{(0)}$  are solutions of the problem set on the real cell  $C_{\vec{x}}$

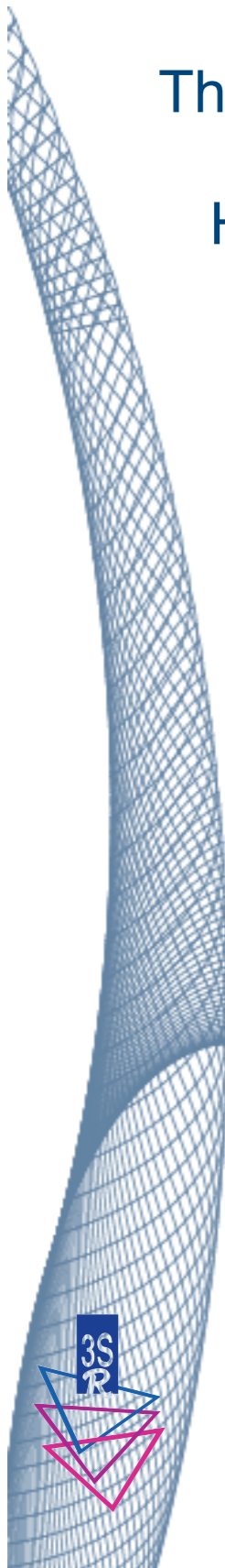
$$\operatorname{div}^{\xi} \vec{\sigma}^{(0)} = 0 \text{ in } Y_{\vec{x}}^e$$

$$\vec{\sigma}^{(0)} = C\left(\frac{\vec{\xi}}{e}\right) \epsilon^{\xi}(\vec{u}^{(1)}) \text{ in } Y_{\vec{x}}^e$$



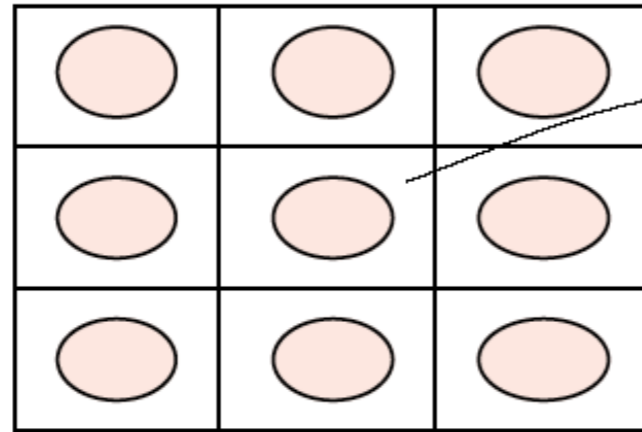
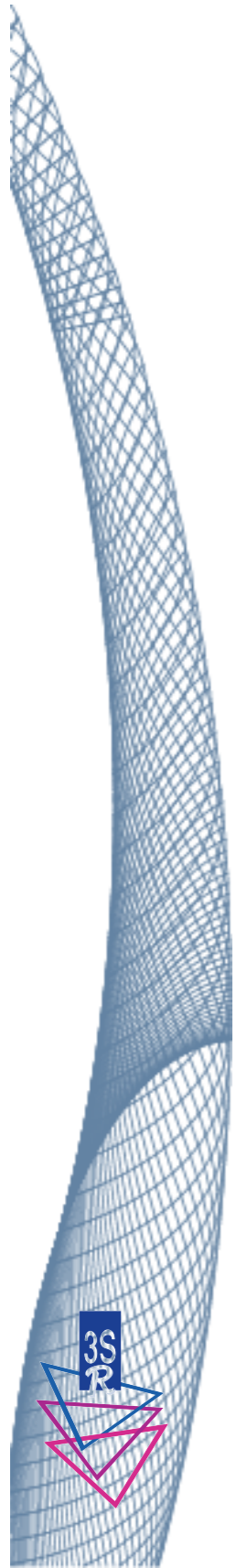
$$\vec{u}^{(1)}(\vec{\xi} + e\vec{Y}^i) - \vec{u}^{(1)}(\vec{\xi}) = \epsilon^x(\vec{u}^{(0)}) \cdot e\vec{Y}^i \text{ on } \gamma_{\vec{x}}^i, i = 1, 2$$

Remak: heuristic method for the bar

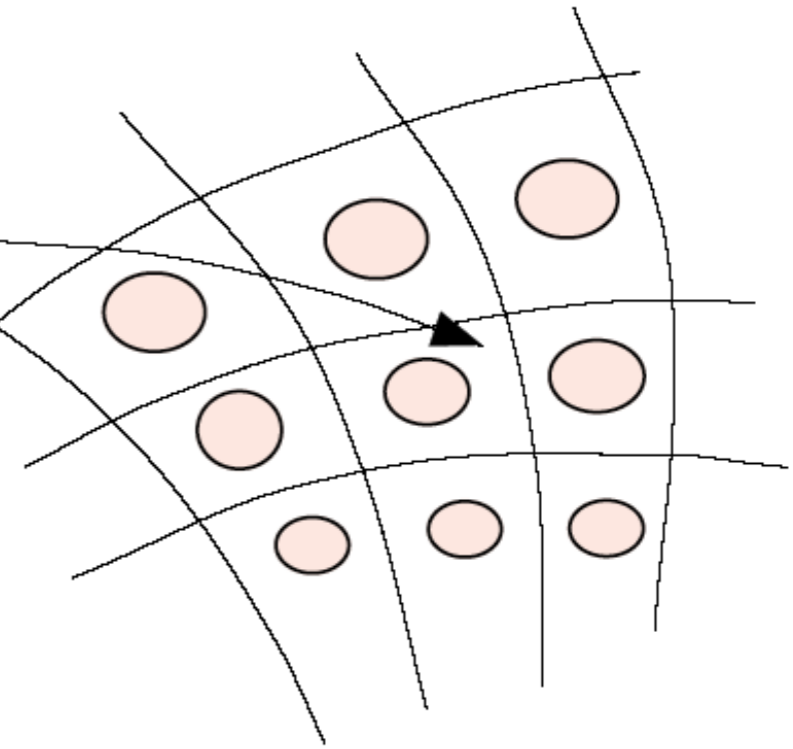




# Quasi periodic media

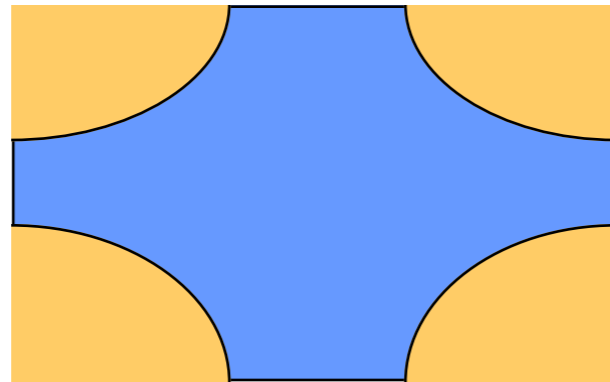
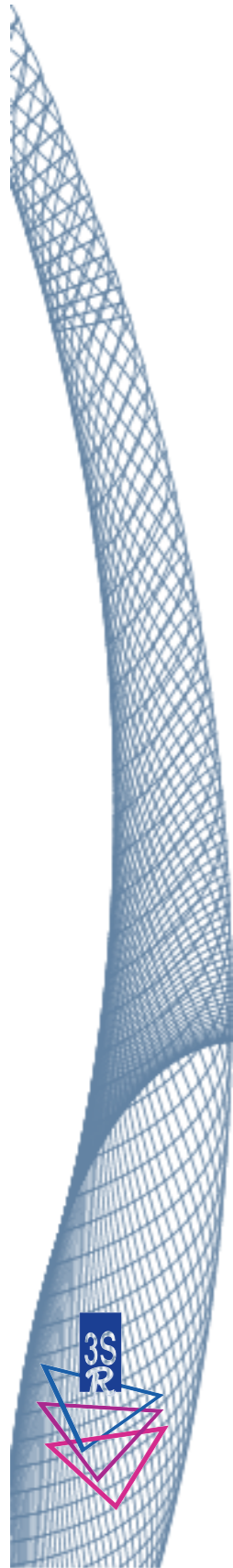


$\phi$



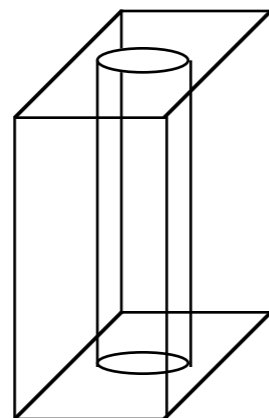
- Applications
- Geometrically quasiperiodic media
- Elastoplastic periodic media
- Large strain framework

# Multiphysics and multi parameter modellings



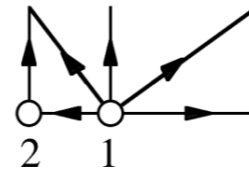
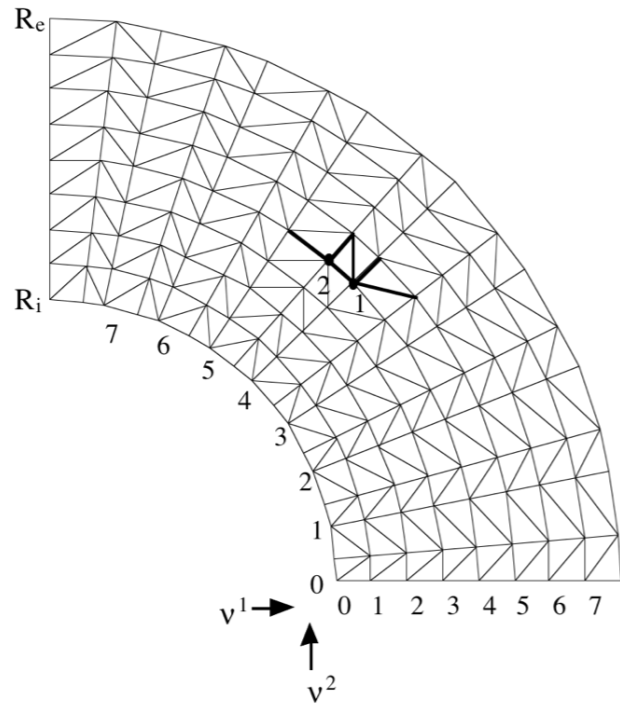
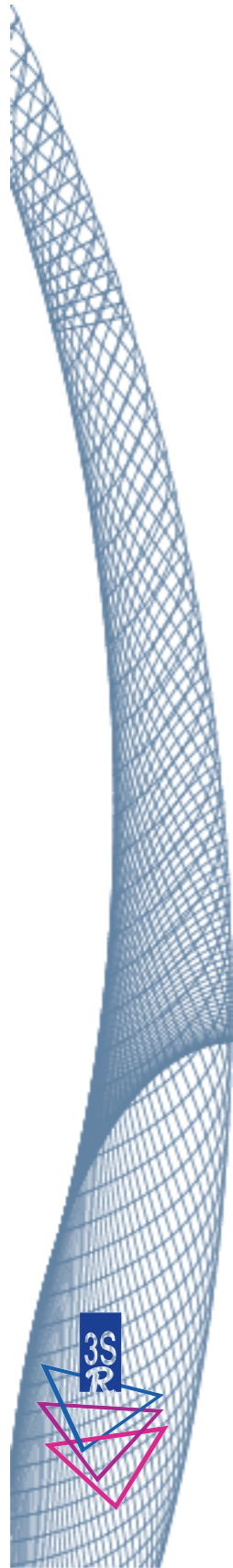
Darcy's law  
Biot's modelling of the consolidation  
Large strains  
Viscosity of the fluid  $\simeq e^2$

Periodic plates or beams



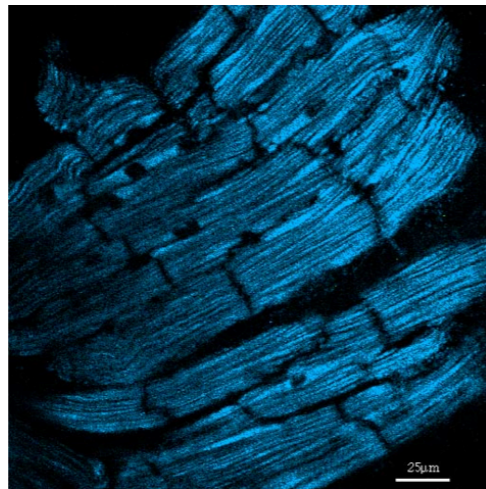
Medium reinforced by slender fibers

# Continuous modelling of discrete structures

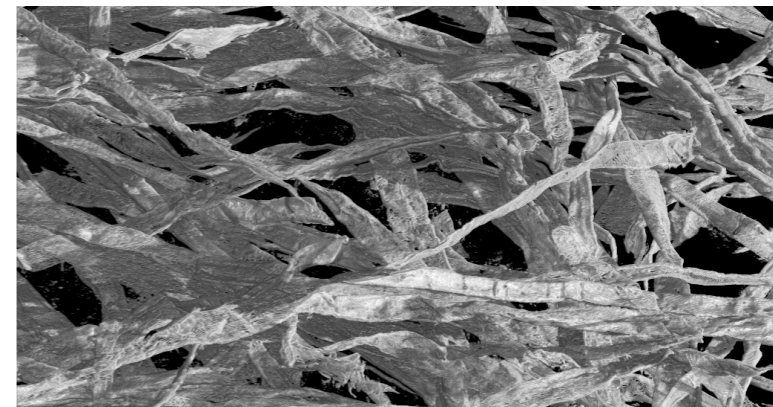


$$\tilde{n} = (\nu^1, \nu^2, n)$$

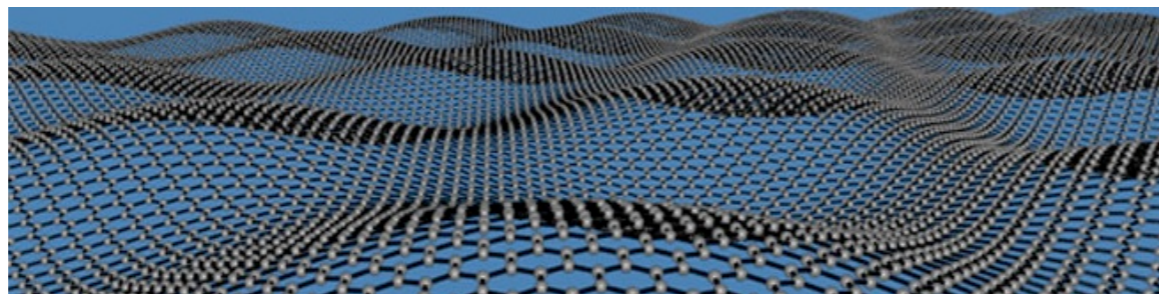
$$\vec{u}^{\tilde{n}} = \vec{u}^{(0)}(e\nu^1, e\nu^2) + e\vec{u}^{(1)n}(e\nu^1, e\nu^2) + \dots$$



Muscle



Paper



Graphene



## Intermediate conclusions and remarks

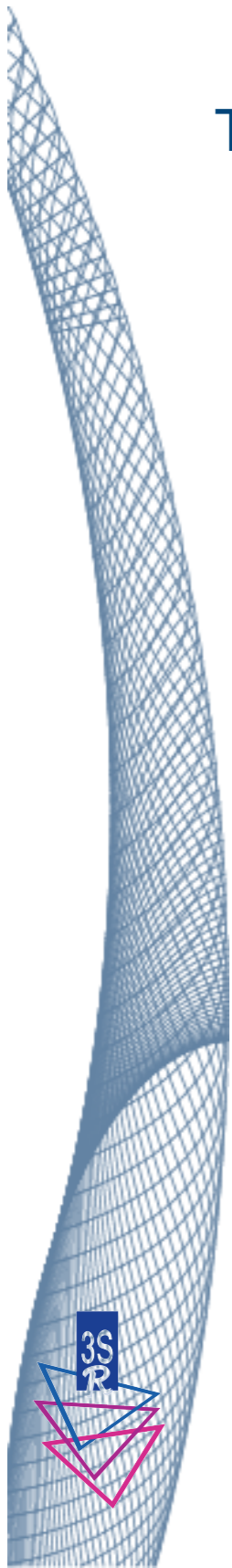
The homogenization method of periodic media is robust in the sense that, starting from the description of the macroscopic scale, it enables to define the equivalent fields at the macroscopic scale and the equations that govern them and that with the only hypothesis of the double scale expansion.

The approximation of the real displacement field is the macroscopic field + a small corrector presenting variations at the micro scale

The macroscopic constitutive equation is given by the solving of a self equilibrium problem on the elementary cell

The macroscopic constitutive equation is invariant under a change of scale in the self equilibrium problem

Hill's lemma is satisfied



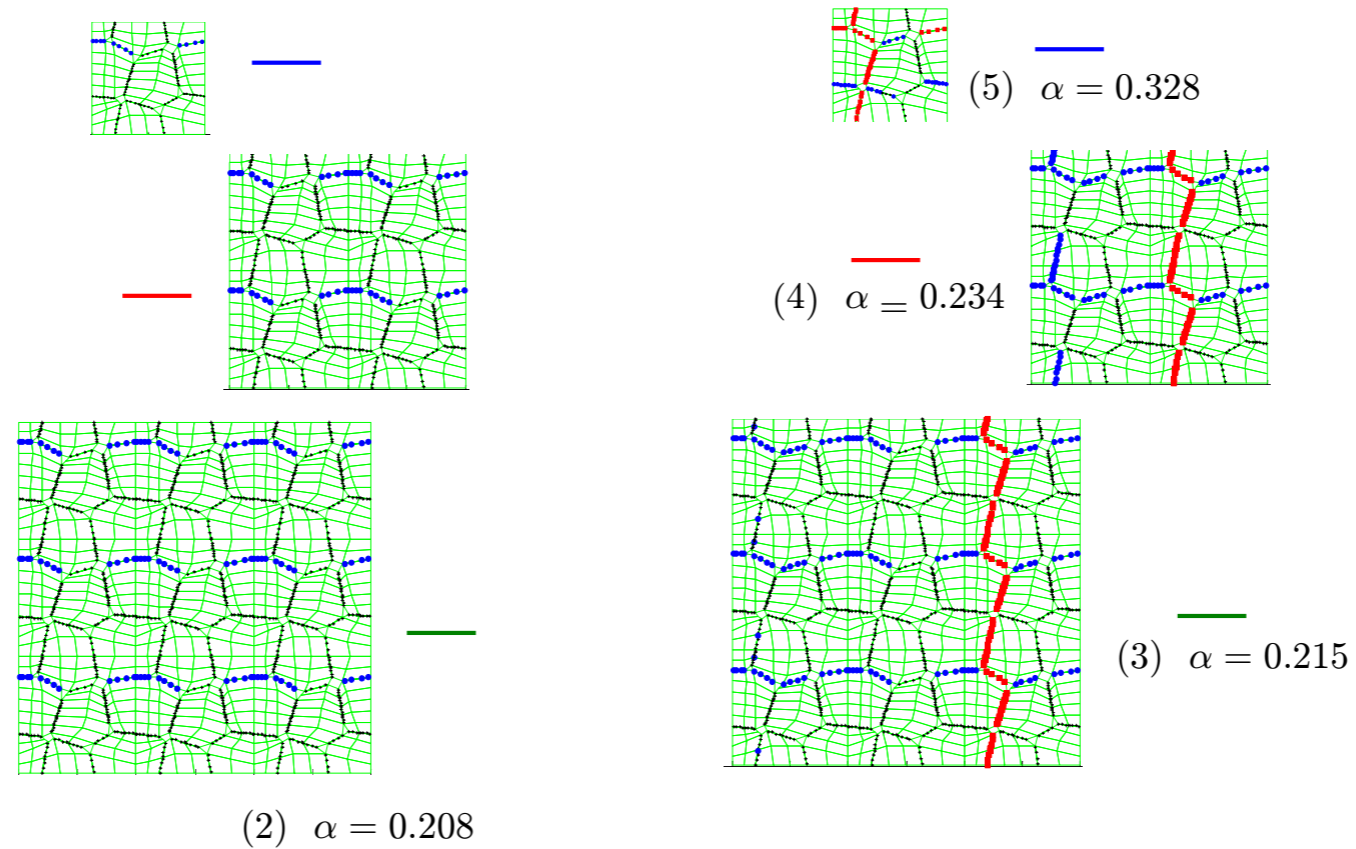
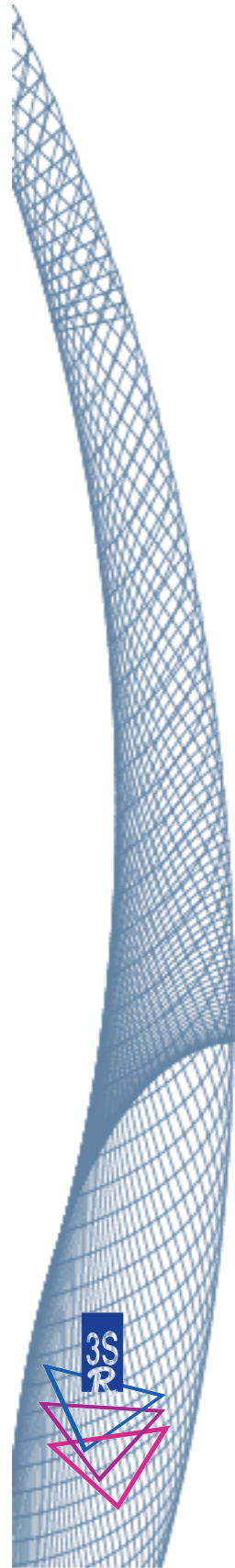
# Limits of the methods

Loss of scale separation

wave propagation

assumed macroscopic quantities that varies at the microscale

Bifurcation



From G. Bilbie's PhD Thesis

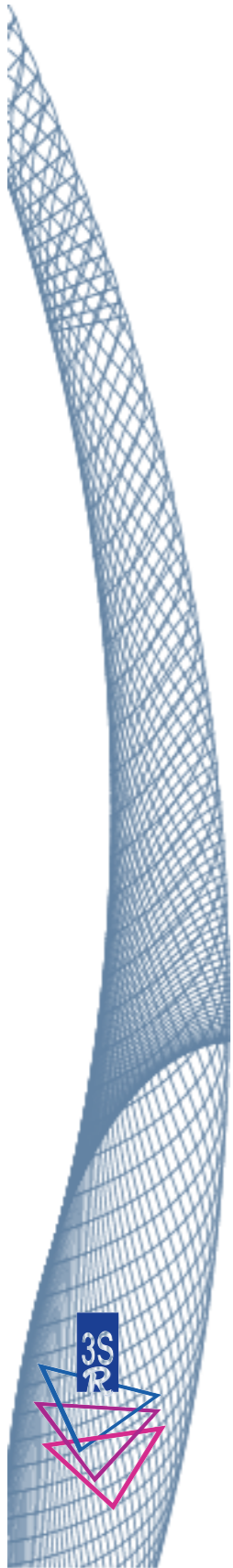
## Parallel with experiments - Representative volume element

Triaxial, biaxial, oedometric tests are designed to be “homogeneous” test

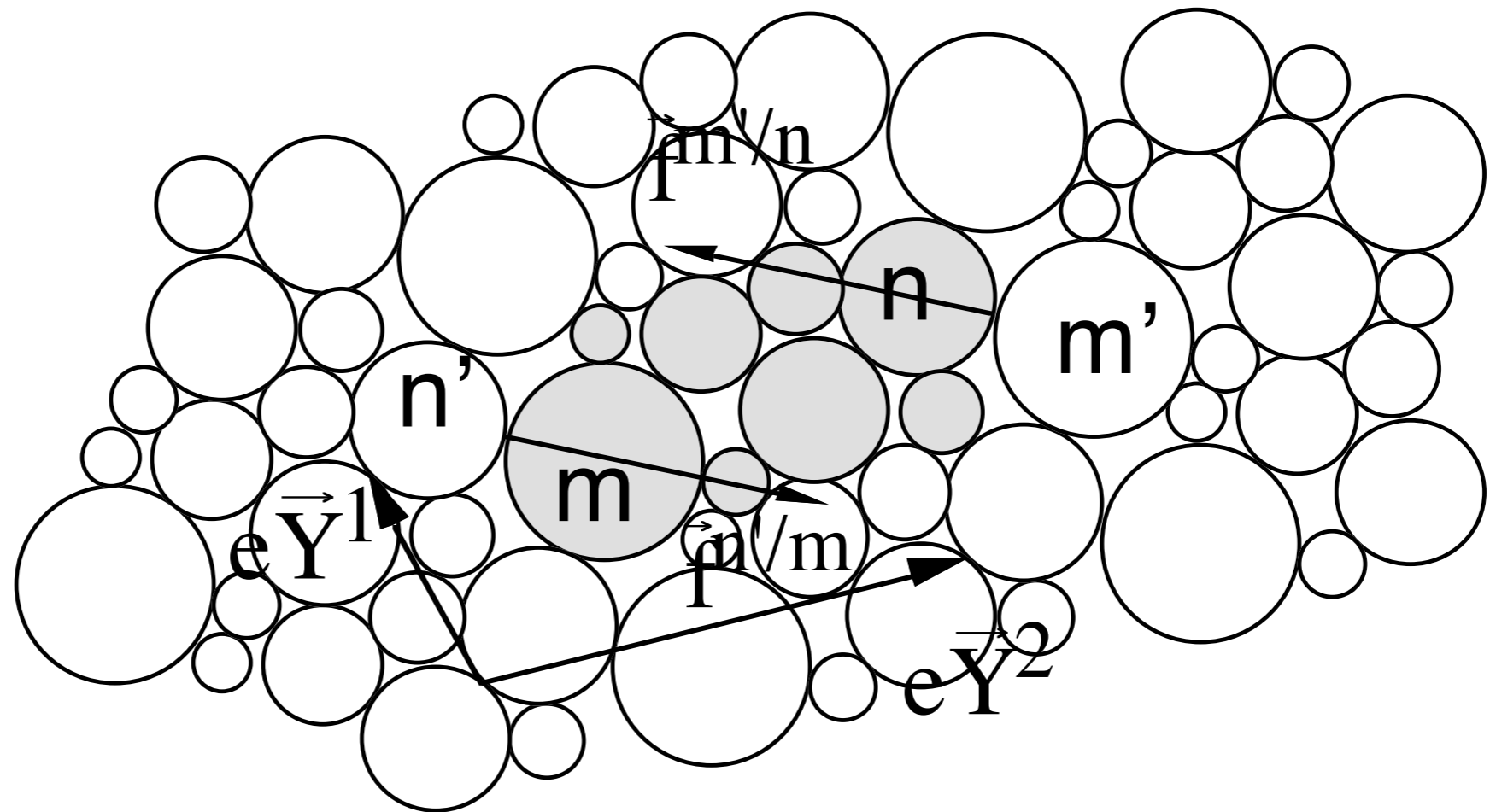
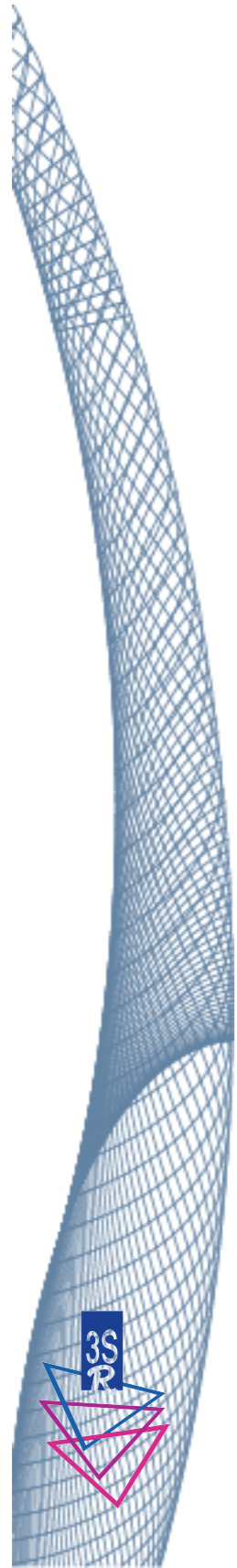
The solving of the self equilibrium problem on the elementary cell is a numerical experiment analogous to the physical one

Hill's definition of the RVE (JMPS 1963)

This phrase will be used when referring to a sample that (a) is structurally entirely typical of the whole mixture on average, and (b) contains a sufficient number of inclusions for the apparent overall moduli to be effectively independent of the surface values of traction and displacement, so long as these values are “macroscopically uniform”. That is, they fluctuate about a mean with a wavelength small compared with the dimensions of the sample, and the effects of such fluctuations become insignificant within a few wavelengths of the surface. The contribution of this surface layer to any average can be made negligible by taking the sample large enough.



# Granular materials



$$\vec{x}^{m'} = \vec{x}^m + eF \cdot \vec{Y}^1$$





Thank you for your attention

